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A SIMPLE PHYSICAL MODEL FOR SPALL FROM NUCLEAR EXPLOSIONS BASED UPON TWO-DIMENSIONAL NONLINEAR NUMERICAL SIMULATIONS

T.G. Barker S.M. Day



Maxwell Laboratories, Inc. S-CUBED Division
P.O. Box 1620
La Jolla, CA 92038-1620

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This technical report has been reviewed and is approved for publication.

JAMES F. LEWKOWICZ

Contract Manager

Solid Earth Geophysics Branch

Earth Sciences Division

JAMES F. LEWKOWICZ

Branch Chief

Solid Earth Geophysics Branch

Earth Sciences Division

FOR THE COMMANDER

DONALD H. ECKHARDT, Director

Earth Sciences Division

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We examine the effect of spall on the source function for explosion waveforms using two-dimensional nonlinear numerical simulations of explosions. A simple, physical model for spall is developed by comparing the complete two-dimensional waveform with the waveform generated by a one-dimensional explosion plus a shallow tension crack in the same layered medium. This is an extension to higher frequencies of the spall model derived by Day, et al. (1983). The tension crack is parameterized by its radius, depth and a distribution of takeoff velocities over its surface. P-waves generated by the two-dimensional simulation are modeled very well by the simple tension crack plus explosion model, and the resulting parameters for the spall model are consistent with the limited set of near-field observations of spall. The model underestimates the shear waves generated in the two-dimensional calculations, indicating that the source of shear waves is more complex than the simple explosion plus tension crack model. P-waves generated by the tension are found to have a narrowband spectrum proportional to ω-5/2 at high frequencies, with a peak typically in the frequency range between 0.5 and 5 Hz, which puts it in the middle of the frequency range where short period magnitudes are commonly measured.				
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1. INTRODUCTION

Several models have been proposed for the spall process that accompanies most nuclear explosions. The models are very difficult to validate directly because (1) the features of the process that can be measured, such as vertical motion at the surface, are observed at only a few locations above the shot, and (2) there are few observations of features such as the depth and area of the spall zone and the distribution of motions within the zone. Two-dimensional nonlinear simulations of the explosion, which include the physics of the free-surface interactions, provide an opportunity to examine spall, and to find simple models to represent it. We present a linear model for the spall process and find its parameters by comparing with the seismic waves from explosion simulations.

Using a form of the elastodynamic representation theorem, we have calculated the short-period body waves emanating from the source zone of the numerical simulations. The implications for teleseismic magnitude measurements were discussed in Day, et al. (1986) and McLaughlin, et al. (1988). By comparing these P and SV wavefields with one-dimensional nonlinear calculations (which do not include the nonlinear effects of the free-surface), we can isolate that part of the wave field due to the nonlinear interaction with the free-surface. We find that a simple tension crack with an opening that propagates with the pP arrival from the explosion fits P-waves from simulations of both Pahute Mesa and Shagan River tests. However, the model which fits the P-wave radiation generates SV-waves that are too small, which indicates that there are additional sources of shear waves in the finite difference simulations.

The tension crack model, proposed in its original form by Day, et al. (1983), is a physical model whose parameters can be compared directly to field observations. The parameters of the model are spall depth and area, detachment velocity, and momentum. The parameters inferred from the simulations are consistent with published estimates of these values. The time dependence of the far-field waveforms is a natural consequence of the model and requires no ad hoc choice of time history to include the effects of source finiteness, the importance of which has been pointed out by Stump (1985). Although there is a trade-off between the parameters of the model, the amplitudes and waveforms from the two-dimensional (2D) simulations tightly constrain the set of parameters which fit the simulations.

The form for the linear source representation of the spall model is such that it can easily be added to a one-dimensional (1D) explosion source to compute regional and teleseismic synthetic seismograms. In a companion paper, McLaughlin, et al. (1990), use the model to compute the effects of spall on synthetic regional explosion seismograms. It is found that the spall contribution to the Lg signal is comparable to the direct explosion contribution.

In the following, we describe the tension crack model and show how it has been implemented. We then compare the body waves from the model with those from the numerical simulations and compare the parameters of the model with field observations. Our conclusions are presented in the last section.

2. THEORY

2.1. Tension Crack in a Layered Medium

Our model for the spall process is a horizontal circular tension crack, shown schematically in Figure 1. The crack lies above the explosion and opens when the free-surface rarefaction from the explosion encounters the crack. The material above the crack is assumed to fly straight up and return under the influence of gravity alone.

We have extended the circular tension crack model of Day, et al. (1983) to include a time dependence which describes the detachment and slap-down of the spall volume as well as the finite size (radius) of the crack. The spall volume in the model is defined as the cylinder whose radius is that of the tension crack and which extends from the crack to the surface. Since we wish to compare the spall model with 2D simulations which were done in a layered medium, we developed the formalism for computing the far-field body waves emanating from a layered medium. The parameters of the model are the crack radius and depth, and the distribution of detachment velocities over the crack.

In this section, we present the complete body wave formalism. We then make some simplifying assumptions to make important features of the time history and spectrum apparent.

We begin with the representation theorem from Aki and Richards (1980), which describes the displacement field due to a discontinuity on a surface Σ :

$$u_n(\underline{x},t) = \iint_{\Sigma} m_{pq}(\xi,t) * G_{np,q}(\underline{x}-\xi,t) d\Sigma$$
 (1)

where

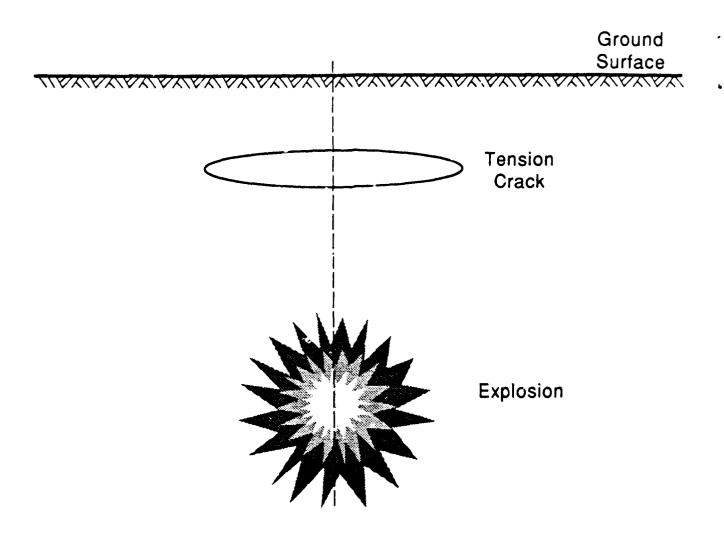


Figure 1. The tension crack model for spall from an explosion.

 \underline{x} is the observer's position,

 ξ is a position on Σ ,

 $G_{np}(x-\xi,t)$ is the Green's function giving the component of displacement in the x_n direction at x due to a force in the ξ_p direction,

 $G_{np,q}(\underline{x}-\xi,t)$ is the gradient of $G_{np}(\underline{x}-\xi,t)$ in the ξ_q direction,

 $m_{pq}(\xi,t)$ is the moment tensor density for the discontinuity, and

* denotes temporal convolution.

For an isotropic medium, the moment tensor density is given by

$$m_{pq}(\xi,t) = \lambda v_k [u_k(\xi,t)] \delta_{pq} + \mu \left\{ v_p [u_q(\xi,t)] + v_q [u_p(\xi,t)] \right\}$$
 (2)

where

 λ and μ are the Lame' parameters (at ξ) for the medium,

 $[\underline{u}]$ is the slip (crack opening) along the discontinuity,

y is the unit normal to the discontinuity, and

 δ_{pq} is the Kronecker delta.

(Repeated indeces indicate summation over three components). For a horizontal tension crack with opening $s(\xi_1, \xi_2, t)$,

$$\underline{\mathbf{y}}^{T} = [0,0,1]$$

$$[\underline{u}]^{T} = [0,0, s(\xi_{1}, \xi_{2}, t)] ,$$
(3)

and the moment tensor density is

$$m = s(\xi_1, \xi_2, t) \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda + 2\mu \end{bmatrix}.$$

The geometry of the problem is shown in Figure 2.

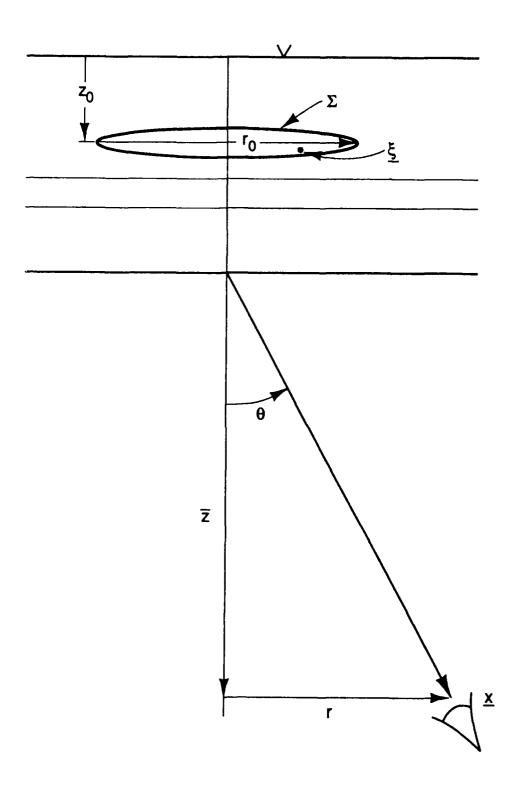


Figure 2. Geometry for a tension crack in a layered medium.

We now specify that the horizontal crack is circular with radius a and that the discontinuity varies only with distance from its center (axially symmetric). Invoking cylindrical symmetry and converting to cylindrical coordinates, the displacement field is

$$u_{n}(\underline{x},t) = \int_{0}^{2\pi} \int_{0}^{a} \left[\lambda \frac{1}{r_{0}} \partial_{r_{0}}(r_{0}G_{nr_{0}}) + (\lambda + 2\mu) \partial_{z_{0}}G_{nz_{0}}\right] * s(r_{0},t) r_{0} dr_{0} d\phi . \tag{4}$$

Here, r_0, ϕ, z_0 are the source cylindrical coordinates

$$\xi_1 = r_0 \cos(\phi)$$

$$\xi_2 = r_0 \sin(\phi)$$

$$\xi_3 = z_0$$

Our objective is to compute the body waves leaving a layered stack. We use the formalism of Fuchs (1966) and Bache and Harkrider (1976). The Fourier transforms of the P wave Green's functions in the notation of Fuchs are given by

$$G_{ij}^{P}(\underline{x},\omega) = -\frac{k_{\alpha}^{-2}}{2\pi} \int_{0}^{\infty} \Delta^{j} K_{ij}^{P} e^{-ikr_{\alpha\alpha}\overline{z}} kdk$$
 (5)

Here, k is the wavenumber for phase velocity c, Δ^j is the downgoing wave potential amplitude due to a force in the j direction, \overline{z} is the vertical distance from the bottom of the stack to the observer,

$$r_{\alpha n} = [(c/\alpha_n)^2 - 1]^{1/2}$$

and $k_{\alpha} = \omega/\alpha_n$, where α_n is the P wave speed in the half-space below the stack. The details on the computation of Δ^j can be found in Fuchs' work. The kernels K_{ij}^P are

$$K_{zz}^{P} = -ikr_{\alpha n}J_{0}(k\overline{r})$$

$$K_{rz}^{P} = -ikJ_{1}(k\overline{r})$$
(6)

$$K_{zr}^{P} = -ikr_{\alpha n}J_{1}(k\overline{r})$$

$$K_{rr}^{P} = \frac{1}{2} k [J_0(k\overline{r}) - J_2(k\overline{r})]$$

where J_{ν} is a Bessel function of the first kind of order ν . The coordinate $\overline{r} = |r - r_0|$, where r is measured from the center of the crack to the observer.

The SV Green's functions are

$$G_{ij}^{SV}(\underline{x},\omega) = -2(\beta_n/c)^2 \frac{1}{2\pi} \int_0^\infty \omega^j K_{ij}^{SV} e^{-ikr_{\beta_n}\overline{z}} kdk , \qquad (7)$$

where the SV potential amplitudes are

$$K_{zz}^{SV} = J_0(k\overline{r})$$

$$K_{rz}^{SV} = -ir_{\beta n}J_1(k\overline{r})$$

$$K_{zr}^{SV} = J_1(k\overline{r})$$

$$K_{rr}^{SV} = \frac{-i}{2}r_{\beta n}[J_0(k\overline{r}) - J_2(k\overline{r})]$$
(8)

Substituting (5) and (6) into (4), we have for the vertical component of the P wave

$$u_z^P(\underline{x},t) = \frac{ir_{\alpha n}}{2\pi k_\alpha^2} \int_0^{2\pi} \int_0^a \int_0^a B(k,\overline{r}) e^{-ikr_{\alpha n}\overline{z}} S(\omega,r_0) k^2 r_0 dr_0 d\phi dk$$
 (9)

where

$$B(k, \bar{r}) = \lambda \, \Delta^{r_0} \frac{1}{r_0} [k r_0 J_0(k \bar{r}) + (1 - r_0 / \bar{r}) J_1(k \bar{r})] + (\lambda + 2\mu) \, \partial_{z_0} \Delta^{z_0} J_0(k \bar{r})$$

Following Fuchs (1966), we evaluate (9) using the saddle point approximation, which is valid for

$$R \equiv \sqrt{\overline{z^2 + r^2}} \gg \sqrt{z_0^2 + r_0^2} \quad , \tag{10}$$

That is, it is good for observer distances much greater than the source radius and depth. Fuchs shows that integrals like (9) can be solved using the relation

$$\int_{0}^{\infty} f(k,\omega) e^{-ikr_{\alpha n}\overline{z}} J_{m}(k\overline{r})dk \approx i^{m+1} f(k,\omega) e^{-ik_{\alpha n}R} r_{\alpha n} R^{-1}.$$
 (11)

Applying this to Equation (9), we have

$$u_{z}^{P}(x,t) = \frac{C_{z}^{P}}{2\pi R} F^{P}(\omega,k) \int_{0}^{2\pi} \int_{0}^{a} e^{-ik_{\alpha\alpha}R} S(\omega,r_{0}) r_{0} dr_{0} d\phi$$
 (12)

where

$$F^{P}(\omega,k) = \lambda \Delta^{r_0}k + (\lambda+2\mu) \partial_{z_0}\Delta^{z_0} ,$$

$$C_z^{P} = -cos^2\theta_P$$

and θ_P is the P wave take-off angle. The wavenumber k is evaluated at the takeoff angle; $k=\omega/c$, $c=\alpha_n/\sin(\theta_P)$. To evaluate the azimuthal integral in (12), we invoke the far-field condition (10), and approximate the slant range R with the lower order terms of its Taylor series,

$$R \approx \hat{r} - \frac{r}{\hat{r}} r_0$$

where

$$\hat{r} = \sqrt{\overline{z}^2 + r^2} .$$

Refering to Figure 2, we see that

$$\frac{r}{\hat{r}} = \sin \theta_P \cos \phi ,$$

so that (12) becomes

$$u_{z}^{P}(x,t) = \frac{C_{z}^{P}}{2\pi R} F^{P}(\omega,k) e^{-ik_{\alpha n}\hat{r}} \int_{0}^{2\pi} \int_{0}^{a} e^{-ikr_{0}\cos\phi} S(\omega,r_{0}) r_{0} dr_{0} d\phi$$
 (13)

Using the integral representation of the Bessel function

$$J_0(\zeta) = \frac{1}{2\pi} \int\limits_0^{2\pi} e^{i\zeta {\rm cos} \varphi} \, d\varphi \ ,$$

we have

$$u_{z}^{P}(\underline{x},t) = \frac{C_{z}^{P}}{R} F^{P}(\omega,k) e^{-ik_{\alpha s}\hat{r}} \int_{0}^{a} S(\omega,r_{0}) J_{0}(kr_{0}) r_{0} dr_{0} . \qquad (14)$$

Applying the same steps to the SV Green's functions (7), we find

$$u_z^{SV}(\underline{x},t) = \frac{C_z^{SV}}{R} F^{SV}(\omega,k) e^{-ik\beta_n \hat{r}} \int_0^a S(\omega,r_0) J_0(kr_0) r_0 dr_0 . \qquad (15)$$

where

$$F^{SV}(\omega,k) = \lambda \omega^{r_0}k + (\lambda + 2\mu) \partial_{z_0}\omega^{z_0} ,$$

$$C_z^{SV} = \sin(2\theta_{SV}) .$$

The radial integral in (14) and (15) can be evaluted numerically, or solved analytically for certain algebraic forms of $S(\omega, r_0)$. Some examples follow. First define

$$P(\omega) = \int_{0}^{a} S(\omega, r_{0}) J_{0}(kr_{0}) r_{0} dr_{0} ,$$

then for constant crack opening

$$S(\omega,r_0) = S_0(\omega)$$
,

we find

$$P(\omega) = \frac{a}{k} J_1(ka) S_0(\omega) .$$

If instead the dependence of crack opening on radius is quadratic,

$$S(\omega, r_0) = S_0(\omega) \frac{(a^2 - r_0^2)}{a^2} ,$$

$$P(\omega) = 2k^{-2} J_2(ka) S_0(\omega) .$$
(16)

Finally, for a Gaussian dependence,

$$S(\omega, r_0) = S_0(\omega)e^{-(r_0/a)^2}$$

 $P(\omega) = \frac{1}{2} a^2 e^{-(ka/2)^2} S_0(\omega)$.

We note that the effective far-field source function under these assumptions is the

Hankel transform of the distribution of displacement on the tension crack. We shall refer to these means of calculating $P(\omega)$ in Section 3. We discuss next the specification of the time history $S(\omega, r_0)$.

2.2. Time History

The model presented here is based on a tension crack which opens due to a tension wave from the free surface. We assume that the material then simply behaves ballistically, and that no restoring forces in the medium add to bring the material back down to its original position. The displacement at each point on the tension crack then has the time history

$$S(t,r_0) = \begin{cases} v(r_0,t_0)\tau - \frac{1}{2}g\tau^2 & \text{for } 0 \le \tau \le 2v(r_0,t_0)/g \\ 0 & \text{for } \tau > 2v(r_0,t_0)/g \end{cases}$$
(17)

where $v(r_0,t_0)$ is the detachment velocity, $\tau=t-t_0$, t_0 is the time of initiation at r_0 and g is the acceleration due to gravity. The form of $v(r_0,t_0)$ can be regarded as a parameter of the model, and we have experimented with various forms of $v(r_0,t_0)$ while fitting the model to numerical simulations. These forms included (1) analytic distributions of initial velocities which initiate at the same instant across the crack (t_0 is constant), (2) random distributions, and (3) distributions which propagate outward with the pP phase from the explosion. The first form allows $P(\omega)$ to be evaluated analytically, as shown above in Section 2.1. $P(\omega)$ must be evaluated numerically for the third form. In this case, we set

$$t_0(r_0) = \sqrt{(2z_s + z_{\exp})^2 + r_0^2} / \alpha$$

and $v(r_0)$ to some algebraic function of r_0 . As we shall see in the next section, the

analytic first form was adequate for the Shagan River simulations, while the third numerical form was required to fit the Pahute Mesa simulations.

Another approach is to view the spall opening as a stochastic process where one has only probabilistic estimates of the process. This allows us to make general statements about the far-field radiation. We assume that the detachment velocities at each point on the crack are distributed randomly between minimum and maximum velocities v_1 and v_2 according to a probability density function $\phi(v)$. We make the bounds explicit by writing

$$\phi(v) = f(v) [H(v-v_1) - H(v-v_2)]$$
.

where

$$\int_{v_1}^{v_2} f(v) dv = 1.$$

The estimate of the separation history is then

$$\overline{S}(t) = \int_{v_a}^{\infty} t (v - v_g) \phi(v) dv .$$

where

$$v_g = \frac{1}{2}gt$$

Introducing the moments of the distribution

$$M_j(a,b) = \int_a^b v^j f(v) dv ,$$

the separation history can be written as

$$\overline{S}(t) = t \left[M_1(v_1, v_2) - v_g \right] \Delta H(0, t_1) +$$

$$t \left[M_1(v_g, v_2) - v_g M_0(v_g, v_2) \right] \Delta H(t_1, t_2)$$
(18)

where

$$t_i = \frac{2v_i}{g} \quad ,$$

and

$$\Delta H(t_1,t_2) = H(t-t_1)-H(t-t_2)$$

is a "boxcar" turning on at t_1 and off at t_2 . We have included the details of the opening history because as we shall see in the next section, the displacement for far-field waves is proportional to the second derivative of $\overline{S}(t)$, which is given by

$$\frac{d^2 \overline{S}(t)}{dt^2} = M_1(v_1, v_2) \, \delta(t) - g \, \Delta H(0, t_1) + \tag{19}$$

$$[\frac{1}{2}v_{g}f(v_{g})-gM_{0}(v_{g},v_{2})]\Delta H(t_{1},t_{2})$$

We note that for any distribution $\phi(\nu)$, the high frequency response will be dominated by the δ function term, which is proportional to the first moment, or the mean velocity of the distribution. This delta function term is the detachment phase which is followed by a free-fall dwell, which is the second term in the equation. The last term is slap down. We will discuss this equation and other features of the model in more detail in the following sub-section.

2.3. Features of the Model

In the following, we make some simplifying assumtions for the purpose of illustrating the features of the model. First, we assume that the earth model is a uniform half-space. In this case, the kernels F^P and F^{SV} become

$$F^{P}(\omega,k) = \frac{-i\omega}{2\alpha^{2}\eta_{\alpha}} \left[(1-2p^{2}\beta^{-2}) \left(e^{-i\omega t_{P}} + R_{pP} e^{-i\omega t_{pP}} \right) + 2\beta^{2}p \eta_{\alpha}R_{sP} e^{-i\omega t_{sP}} \right]$$
(19)

and

 $F^{SV}(\omega,k) = \frac{i\omega}{4\beta^2\eta_{\alpha}} \left[2p \,\eta_{\alpha} sP \, \left(e^{-i\omega t_S} - R_{sS} e^{-i\omega t_{sS}} \right) - \left(1 - 2p^2\beta^{-2} \right) R_{pS} e^{-i\omega t_{pS}} \right] (20)$ where p = 1/c is the slowness, and $\eta_{\alpha}^2 = \alpha^{-2} - p^2$. The travel times for the P, pP, sP, S, pS and sS phases are denoted by t_P , t_{pP} , t_{sP} , t_S , t_{pS} and t_{sS} , respectively. The variables R_{pP} , R_{sP} , R_{pS} , and R_{sS} are the corresponding free surface reflection coefficients (for potentials), given by

$$\begin{split} R_{pP} &= [4\eta_{\alpha}\eta_{\beta}p^2 - (\beta^{-2} - 2p^2)^2]/\,D_R \quad , \\ R_{sP} &= -4\eta_{\beta} \; (\beta^{-2} - 2p^2)/\,D_R \quad , \\ R_{pS} &= 4\eta_{\alpha} \; (\beta^{-2} - 2p^2)/\,D_R \quad , \end{split}$$

with

$$R_{sS} = R_{pP}$$
 ,
$$D_R = 4\eta_{\alpha}\eta_{\beta}p^2 + (\beta^{-2}-2p^2)^2$$

Long Period Limits

We note first that the DC values of F^P and F^{SV} approach zero at least as fast as ω^2 . In addition to the factor of ω in (19) and (20), the quantities

$$(1+2p^2\beta^{-2})(1+R_{pP}) + 2\beta^2 p \eta_{\alpha}R_{sP}$$

and

$$2\beta^2 p \,\eta_{\alpha} \,(1-R_{pS}) - (1-2p^2\beta^{-2}) \,R_{pS}$$
 ,

(the limits of the functions in brackets in (19) and (20) as $\omega \rightarrow 0$), are identically zero. As pointed out by Day (1983), the spall process should contribute no net force or momentum.

Small Take-off Angle Approximation

Next, we restrict our attention to steep take-off angles (small θ_P and θ_{SV}). Expanding the reflection coefficients to second order in take-off angle, we find

$$R_{pP} = -1 + (\frac{\beta}{\alpha})^3 \theta_P^2 ,$$

$$R_{sP} = -4 \frac{\beta}{\alpha} \theta_P ,$$

$$R_{pS} = 4 \frac{\beta}{\alpha} \theta_{SV} ,$$

$$R_{sS} = -1 + \frac{\beta}{\alpha} \theta_{SV}^2 .$$

Expanding the remaining quantities in (19) and (20), we find to $O(\theta_{SV}^2)$ that

$$F^{P} = \frac{i\omega}{\alpha} \left\{ \left[1 - 2\left(\frac{\beta}{\alpha}\right)^{2}\theta_{P}^{2}\right] \left(e^{-i\omega t_{P}} - e^{-i\omega t_{pP}}\right) - 8\left(\frac{\beta}{\alpha}\right)^{3}\theta_{P}^{2}\left(e^{-i\omega t_{pP}} - e^{-i\omega t_{sP}}\right) \right\}$$
(21)

$$F^{SV} = \frac{i \omega}{\beta} \theta_{SV} \left(e^{-i \omega t_S} + e^{-i \omega t_{sS}} - 2e^{-i \omega t_{pS}} \right)$$
 (22)

Axial symmetry demands that the SV motion be zero as $\theta_{SV} \rightarrow 0$, as seen in (22). For small angles, the P wave motion is dominated by the P and pP phases, which for small depths of the tension crack, appear in (21) as a numerical first difference operator.

Approximation for Periods Long Compared to Travel Time to the Surface

The values of the depth of the tension crack that we infer from the numerical simulations in Section 3 are less than 200 m. The P-pP travel time for the Pahute Mesa model is about 0.25 seconds, and less than one-half that for the Shagan River model. So for frequencies much less than about 4 Hz, $\omega(t_P-t_{pP})\ll 1$, and

$$e^{-i\omega t_P} - e^{-i\omega t_{PP}} \approx 2i\,\omega\eta_{\alpha}z_s\,\,e^{-i\,\omega t_P} \quad . \tag{23}$$

Then (21) becomes (to 0^{th} order in θ_P),

$$F^{P} = \frac{-\omega^{2} z_{s}}{\alpha} e^{-i\omega t_{P}} \tag{24}$$

Recall Equation (14), for the P wave displacement. The motion along the ray is approximated by

$$u_{ray}^{P}(\omega) = \frac{\omega^{2} z_{s}}{\alpha^{2} R} e^{-i \omega t_{P}} P(\omega) . \qquad (25)$$

Assuming that crack opening is constant, and taking the inverse Fourier transform of (25), we obtain

$$u_{ray}^{P}(t) = \frac{z_s}{p^2 \alpha^2 R} \left[(ap)^2 - t^2 \right]^{1/2} * \ddot{S}_0(t - t_P) . \tag{26}$$

Finally, we assume that the periods of interest are also longer than ap, the time it takes for a wave to travel across the tension crack. Typical teleseismic values of p are less than 0.1 sec/km and values of a are around 1 km, so pa < 0.1 sec. In this case, we can write

$$p^{-2} [(ap)^2 - t^2]^{1/2} = \frac{1}{2} \pi a^2 \delta(t)$$
,

(26) becomes

$$u_{ray}^{P}(t) = \frac{m_{spall}}{2(\lambda + 2\mu)R} \ddot{S}_{0}(t - t_{P}) ,$$
 (27)

where $m_{spall} = \rho \pi z_s a^2$ is the mass of the material lifted by the spall process. The P-wave amplitude is then proportional to the spall mass, and the opening acceleration \ddot{S} . Recall that in Section 2.2, we proscribed the opening history for a distribution of detachment velocities. We assume the distribution is uniform (f(v)=1) between velocities v_1 and v_2 , evaluate (19), and substitute the result in (27):

$$u_{ray}^{P}(t) = \frac{m_{spall}}{2(\lambda + 2\mu)R} \left[\overline{v} \ \delta(t') - g \, \Delta H(0, t'_1) + \right]$$
 (28)

$$\frac{g}{v_2 - v_1} \left(-v_2 + \frac{3}{4} gt' \right) \Delta H(t'_1, t'_2)$$

where $t'=t-t_P$ and $\overline{v}=(v_1+v_2)/2$. Equation (28) is shown schematically in Figure 3. The inital δ function term is proportional to $m_{spall}\overline{v}$, the mean spall momentum. The dwell term is $m_{spall}g$, the gravitational restoring force. The duration of the dwell is t_1 , and that of the slap down is t_1-t_2 .

The far-field SV displacement is approximated by

$$u_{ray}^{SV}(t) = \frac{\pi a^2}{\beta R} \theta_{SV} \dot{S}(t) * [\delta(t - t_S) + \delta(t - t_{SS}) - 2\delta(t - t_{pS})]$$
 (29)

Spectral Characteristics

The spectrum of the body waves from the tension crack model is a narrowband signal. To see this, consider Equation (25). As $\omega \to 0$, $P(\omega)$ approaches a constant proportional to the area of the crack, so the far-field displacement approaches zero as ω^2 . This is the case for any type of dependence of opening on r_0 . The frequency limit depends on the details of $S(\omega, r_0)$, but we can make some general statements. Using the time dependence discussed above in Equation (19), it can be shown that at high frequencies, $S(\omega)\approx M_1(v_1,v_2)$, the mean detachment velocity. Then

$$P(\omega) \approx M_1 \int_0^a S(r_0) r_0 dr_0 .$$

For constant opening (Section 2.1), upon using the asymptotic approximation for the Bessel function,

$$u_{ray}^{P}(\omega) \approx \omega^{-3/2} \frac{z_s}{\alpha^2 R} e^{-i\omega t_P} P(\omega) \cos(ka - 3\pi/4)$$
, (25)

which rolls off at a rate of $\omega^{-3/2}$ at high frequencies. However, for a crack opening distribution which goes to zero at the edge of the crack, the roll off is faster. Consider

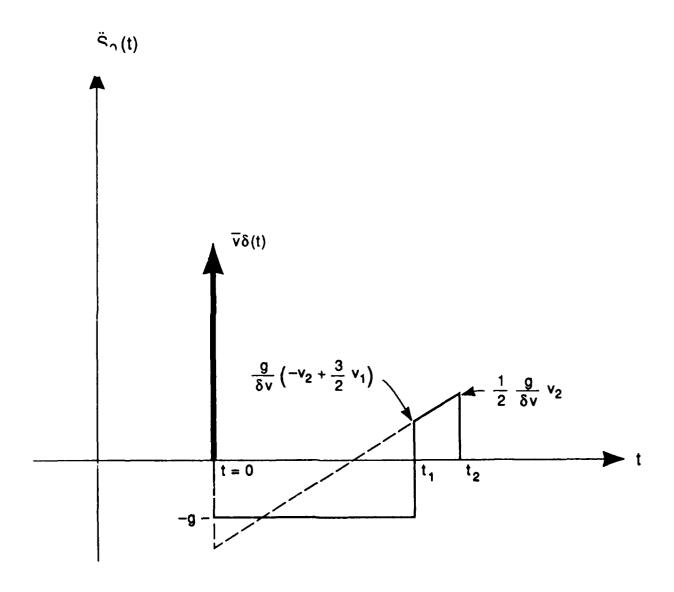


Figure 3. Schematic drawing of the detachment acceleration history which is proportional to the far-field P-wave displacement.

a distribution

$$S_0(r_0) = 1 - (\frac{r}{a})^n$$
,

where n is a positive integer. With a little manipulation,

$$P(\omega) \approx M_1 \frac{1}{(ka)^n} \frac{n}{k^2} \int_0^{ka} \zeta^n J_1(\zeta) d\zeta$$
,

where $\zeta = kr_0$. It can be shown that at high frequencies, this expression is proprotional to k^{-2} , so that the displacement rolls off at $\omega^{-5/2}$. Thus, any radial dependence which goes to zero as fast as a power of r_0 , will have a roll off of $\omega^{-5/2}$. The spectrum is shown schematically in Figure 4. Since explosion models typically decay as ω^{-2} at high frequencies, and are flat at low frequencies, the tension crack will be a more narrowband signal than the explosion by itself. Thus, if the spall contribution is comparable to that of the explosion, it will be so only in a narrowband.

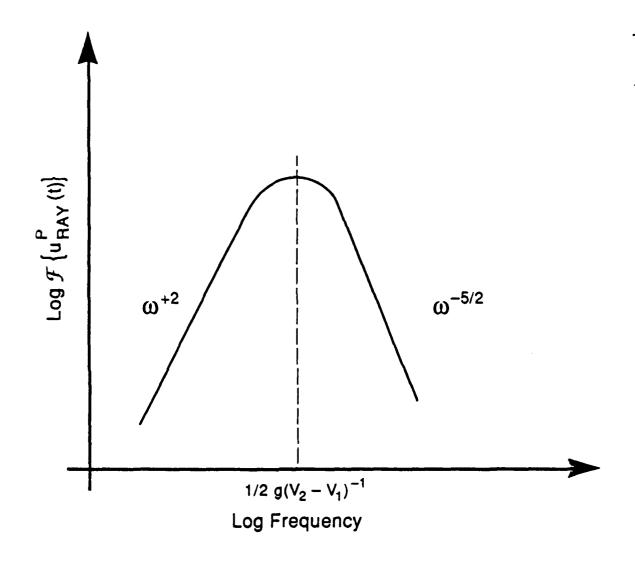
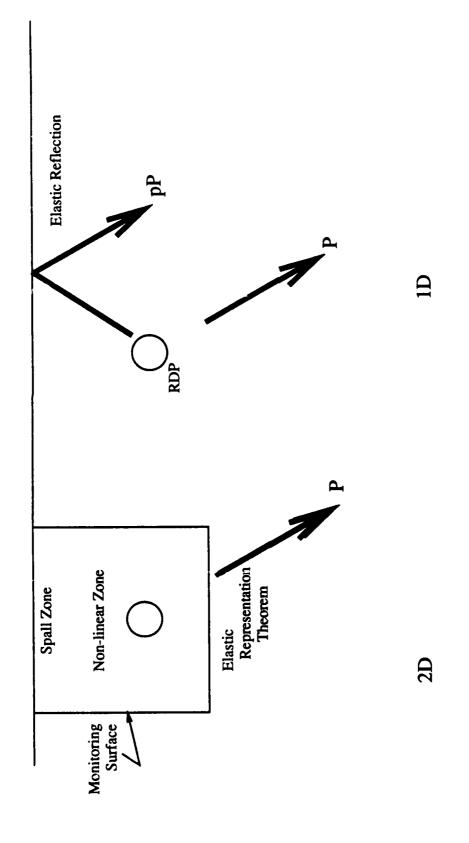


Figure 4. Schematic drawing of far-field P-wave displacement spectrum.

3. COMPARISON WITH NUMERICAL SIMULATIONS

The objective of this study was to derive a simple, linear physical model which represents the spall process. Our strategy has been to isolate source interaction effects by comparing the wavefields from 2D calculations, u_{2D} , with those from 1D calculations done, u_{1D} , in the same source materials (but in an inifinite medium). Our working assumption is that the difference in the wavefields represents the free surface interaction effects, as sketched in Figure 5. In fact, the procedure has been to find the difference in the displacements $u_{2D}-u_{1D}$, and vary the parameters of the model (described in the previous section) to fit the displacements u_{spall} . Alternatively, we could have found u_{spall} which satisfies $u_{1D}+u_{spall}=u_{2D}$. We found the first approach to be more direct.

To find the ground motions from the 2D calculations, we used the methods described in Rodi, et al. (1978), Bache, et al. (1982), and Day, et al., (1983, 1986). The 2D simulations themselves are described in Day, et al. (1986). The elastic properties for the Pahute Mesa and Shagan River simulations are shown in Table 3.1. The method for computing the body waves entails evaluating a form of the elastodynamic representation theorem, which gives the motions in terms of spatial and temporal convolutions of displacements and stresses monitored on a surface surrounding the nonlinear zone with Green's functions and their spatial gradients.

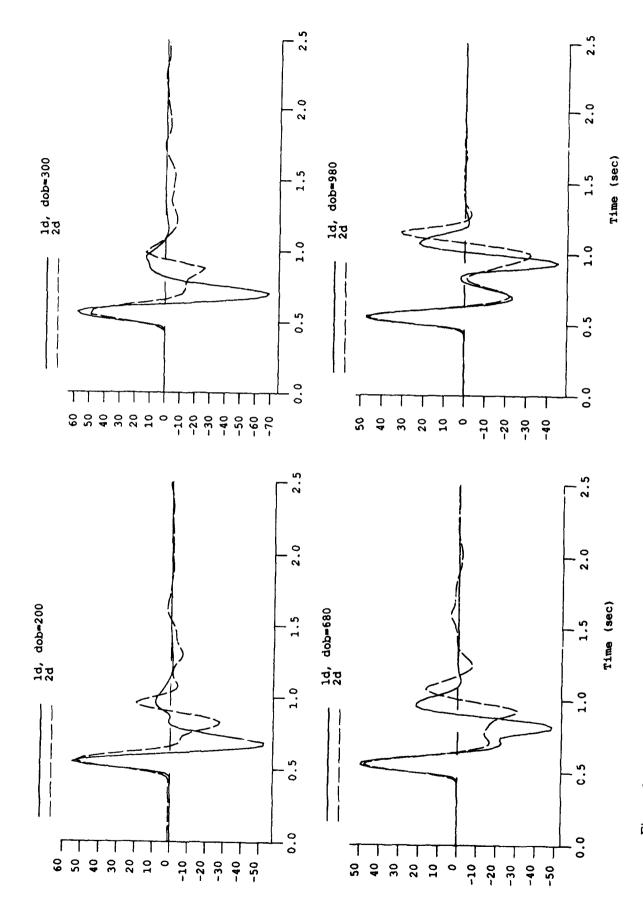


Sketch of the P-waves from the 2D nonlinear simulations (left) and 1D cases (right) in which an RDP (from a 1D nonlinear simulation) is embedded in an elastic medium. Figure 5.

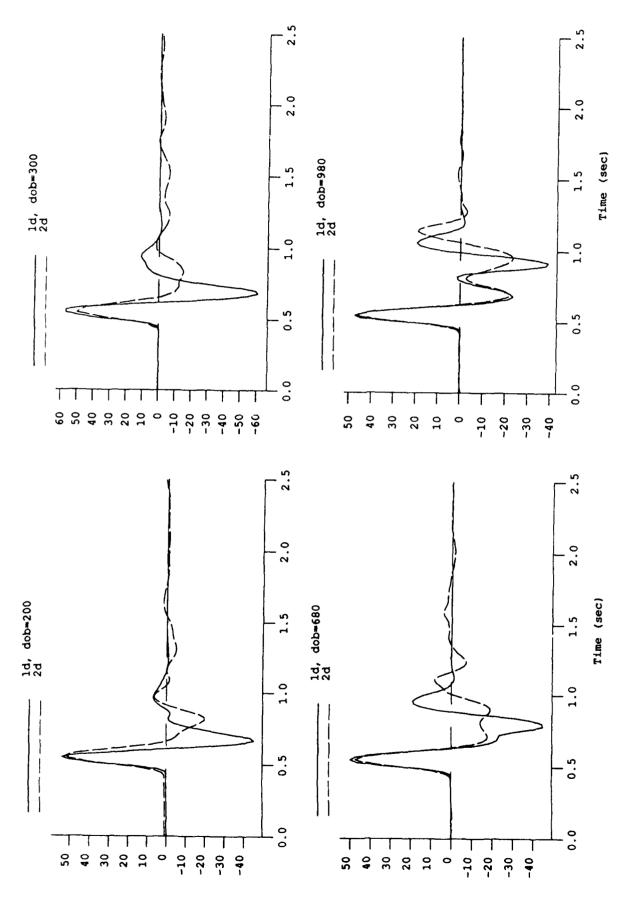
Table 3.1				
Elastic St	Elastic Structure for the Shagan River Simulations			
Leyer	Compressional	Shear	Density	
Thickness	Velocity	Velocity		
(m)	(m/sec)	(m/sec)	Kg/m^3	
∞	5018	2789	2700	
Elastic Structure for the Pahute Mesa Simulations				
Layer	Compressional	Shear	Density	
Thickness	Velocity	Velocity		
(m)	(m/sec)	(m/sec)	Kg/m^3	
112.5	1208	661.4	1600	
457.5	2025	1109	1950	
∞	2887	1581	2000	

3.1. Shagan River Simulations

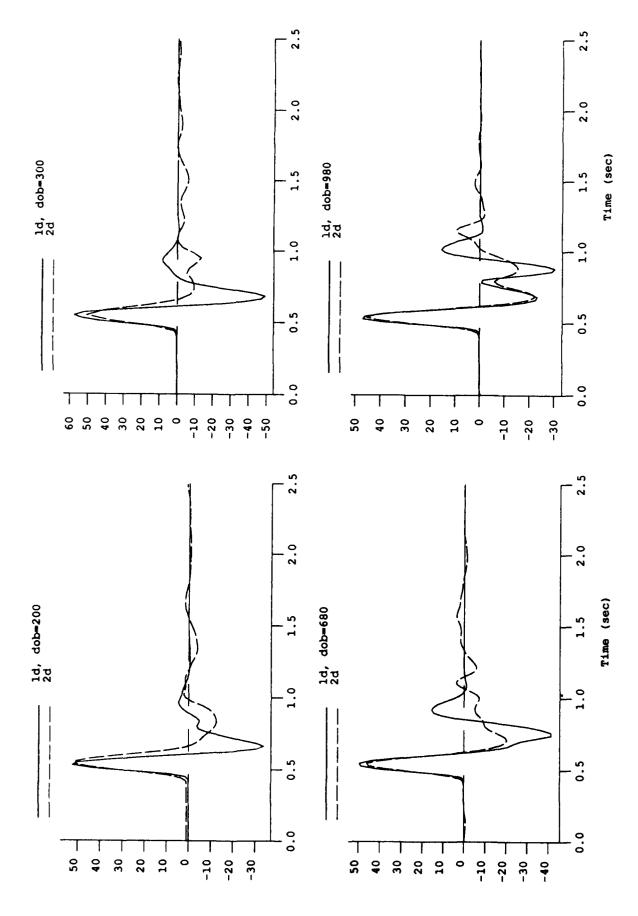
We begin with the Shagan River simulations, which were all done at a yield of 125 KT and at three depths of burial (DOB): an over buried depth (980 m), an optimally buried depth (680 m), a depth just below cratering (no ejecta) (300 m), and a depth which causes cratering (200 m). The results for P waves were presented in Day, et al. (1986), and we include them here for purposes of comparing with the spall model. As can be seen in Table 3.1, the earth model is a half-space, with material properties representing typical values for the high velocity near surface media at the site. The far-field P and SV displacements are shown for three take-off angles in Figures 6 to 11. The take-off angles, 10°, 20° and 30°, are representative of teleseismic, intermediate and regional slownesses (phase velocities) for this source structure. The motions from the 2D simulations are overlain with 1D simulations in which the non-linear properties at the source are the same as the 2D values. The 1D source (RDP) was inferred, and the body waves were calculated for a linear elastic medium. Thus, for the Shagan River half-space model, the 1D waveforms have the direct P phase, as



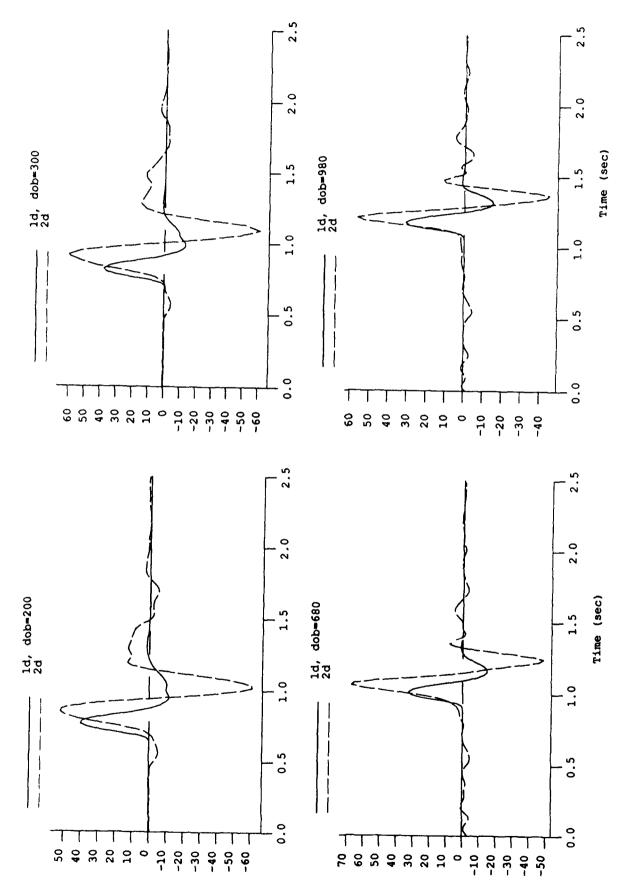
Comparison of the far-field P-waves from the 1D (solid lines) and 2D (dashed lines) Shagan River simulations for four depths of burial at a take-off angle of 10°. Figure 6.



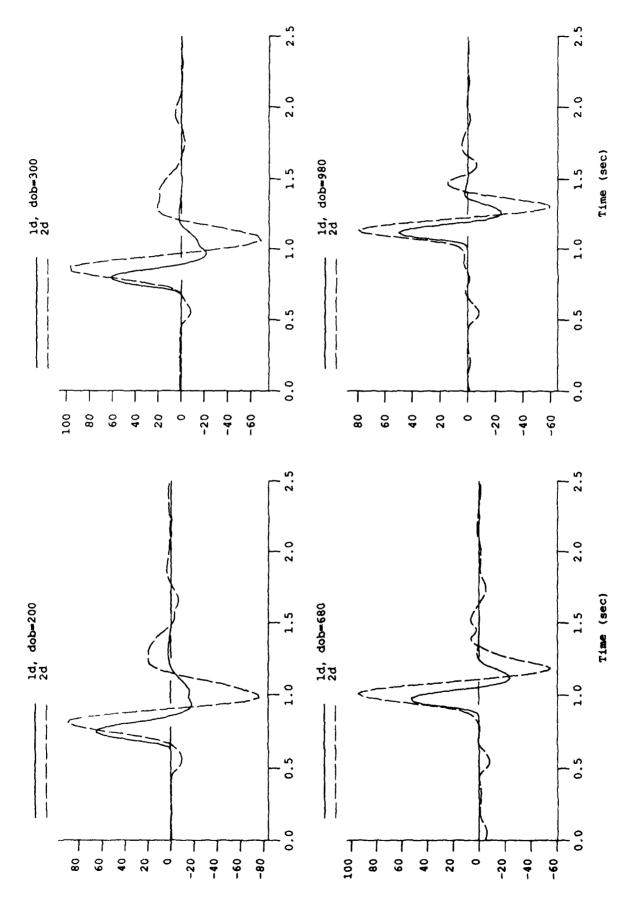
Comparison of the far-field P-waves from the 1D (solid lines) and 2D (dashed lines) Shagan River simulations for four depths of burial at a take-off angle of 20°. Figure 7.



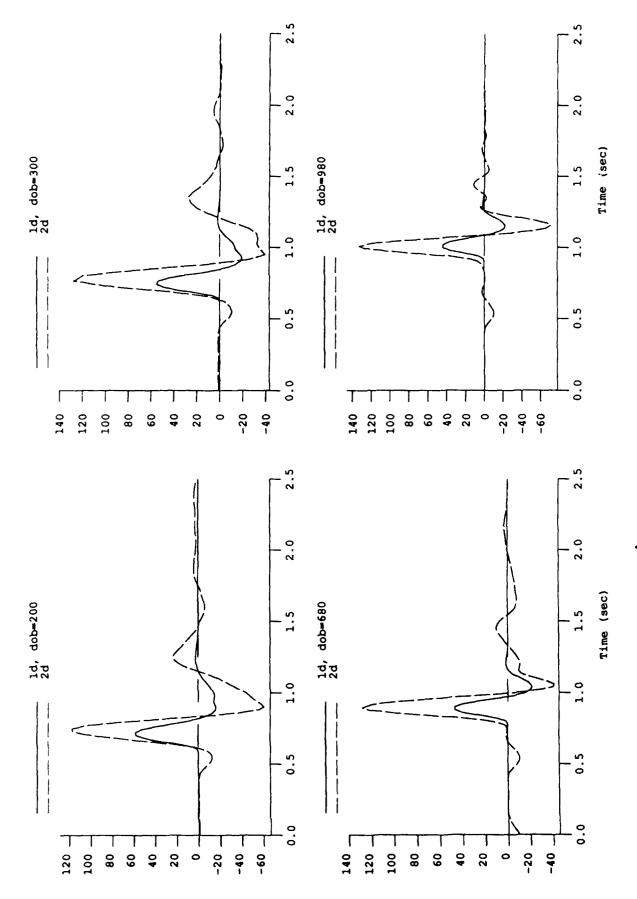
Comparison of the far-field P-waves from the 1D (solid lines) and 2D (dashed lines) Shagan River simulations for four depths of burial at a take-off angle of 30°. Figure 8.



Comparison of the far-field SV-waves from the 1D (solid lines) and 2D (dashed lines) Shagan River simulations for four depths of burial at a take-off angle of 10°. Figure 9.



Comparison of the far-field SV-waves from the 1D (solid lines) and 2D (dashed lines) Shagan River simulations for four depths of burial at a take-off angle of 20°. Figure 10.



Comparison of the far-field SV-waves from the 1D (solid lines) and 2D (dashed lines) Shagan River simulations for four depths of burial at a take-off angle of 30°. Figure 11.

well as the pP and pS elastic reflections. These signals do not include the effects of mantle or crustal propagation, anelastic attenuation, or recording instrumentation.

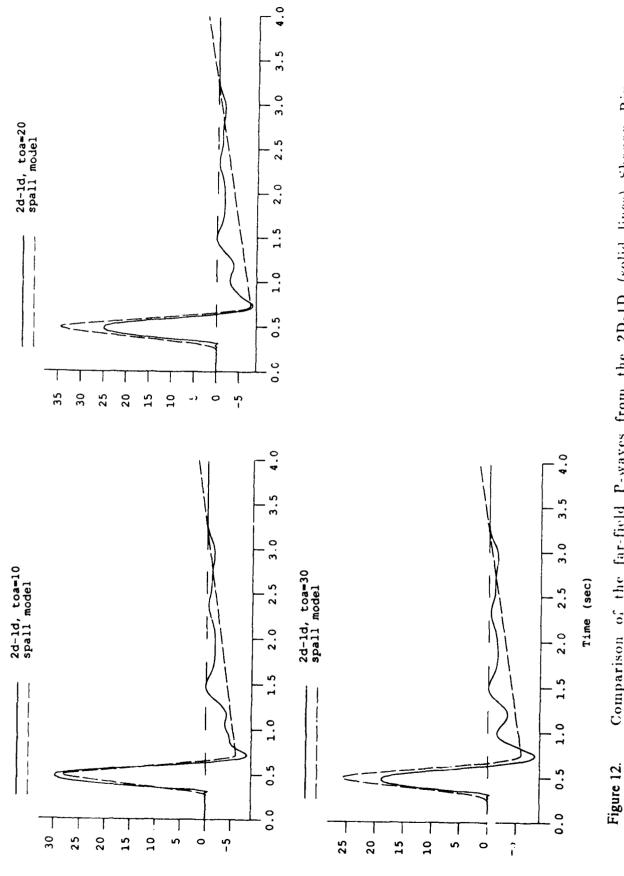
In each case, the rise time and amplitude of the first peak in the P waves (Figures 6-8) is very nearly the same for the 1D and 2D calculations. For the shallow calculations, 200 and 300 m, the 1D and 2D waveforms diverge after the peak and are quite different at later times, indicating that the cratering and near-cratering processes are indeed different from elastic pP reflections. For the deeper DOB's, 680 and 980 m, the apparent pP phase on the 2D records appears to be diminished and delayed relative to the 1D case.

The SV waves (Figures 9-11) show much greater differences between the 1D and 2D cases. The 2D solutions have a direct S wave, due to vertical asymmetries in the source, which is not in the 1D solutions. The main peaks in the 2D SV waves are larger than the 1D peaks at all four DOB's, and are about twice as big for 300, 680 and 980 depths. The duration of the main peaks is also greater for the 2D cases. A large negative swing occurs on the 2D waveforms, which is much smaller on the 1D signals.

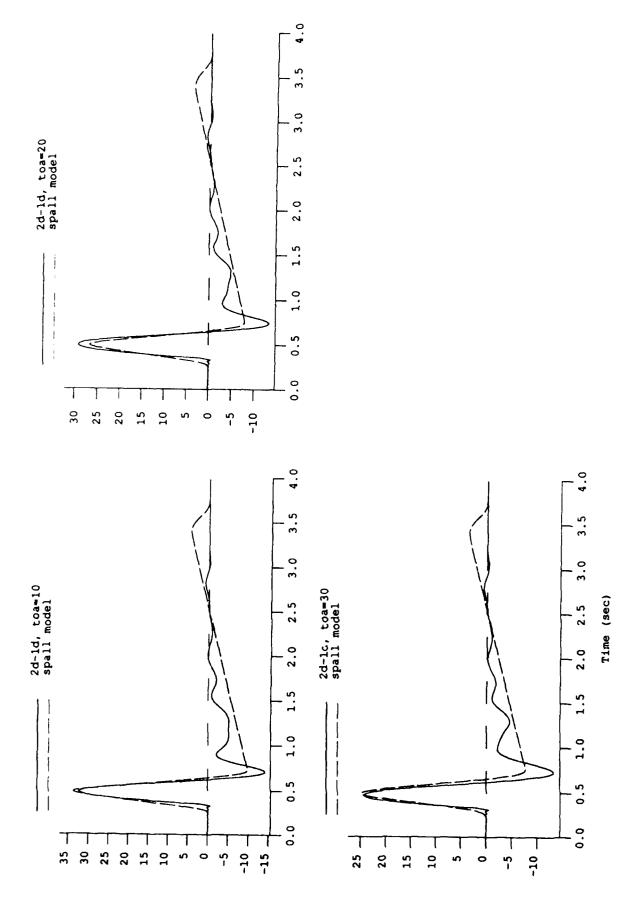
As discussed above, we computed the 2D-1D waveforms and matched them to those from the spall model. The parameters of the spall model which most closely matched the numerical simulations are:

Table 3.2									
Spall Model Parameters for the Shagan River Simulations									
Depth	Crack	Crack	Minimum	Maximum					
of Burial	Depin	Radius	Detachment	Detachment					
ĺ			Velocity	Velocity					
z _{exp}	z_s	a	v_1	v_2					
(m)	(m)	(m)	(m/sec)	(m/sec)					
200	100	600	1.1	20.0					
300	150	600	1.1	15.C					
680	200	600	1.1	4.0					
980	200	600	1.1	1.5					

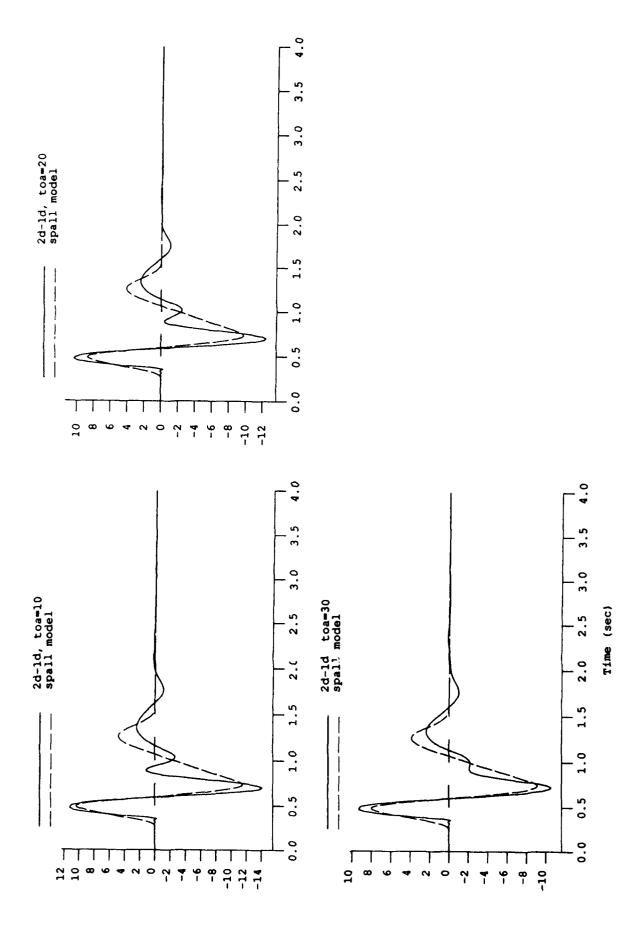
The theoretical waveforms were found to be weakly dependent on the form of the source function $S(\omega, r_0)$ in this case, so it was assumed constant. In Figures 12 through 15, we compare the P wave spall model waveforms with the 2D-1D waveforms for each of the DOB's. In general, the comparisons are quite good, both in amplitude and shape. The parameter that varies the most in Table 3.2 is the maximum detachment velocity v_2 . Recall that in Equation (28), Section 2.3, v_2 enters the solution in two ways. First, the δ function term, which causes the first peak in the waveforms, is proportional to the mean detachment velocity \overline{v} . Second, the duration of the signal (end of slap-down) is time $t_2 = 2v_2/g$. As the DOB decreases, the 2D-1D difference waveforms increase in amplitude and duration. Thus, as the DOB decreases, v_2 is required to increase. We note that, even in the case where cratering occured (200 m), the tension crack model provided a good representation of the P radiation. The shapes of the signals for the 980 m case agree well. For the 680 m case, the agreement is good except for an additional inflection in the later parts of the 2D waveforms that is not modeled by the tension crack.



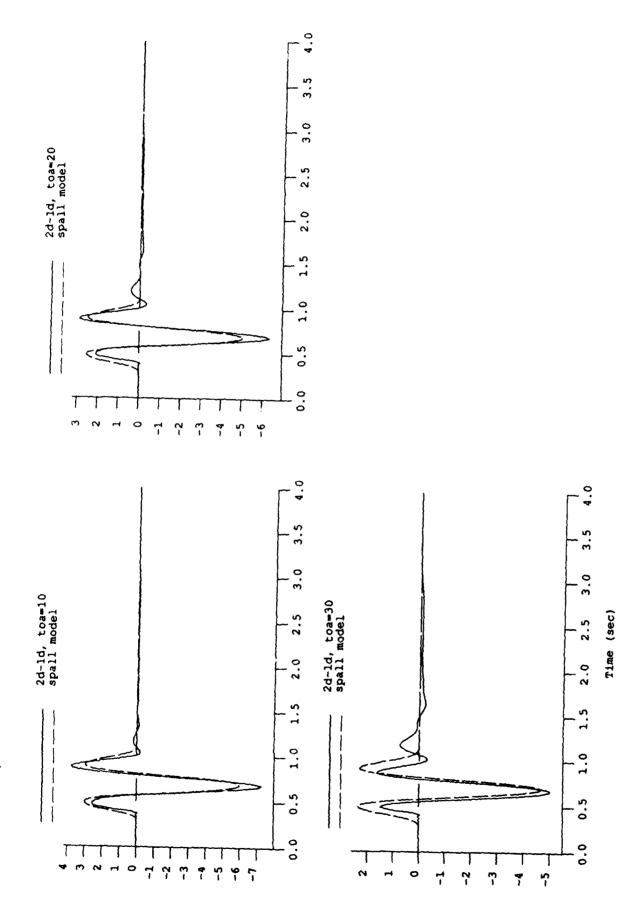
Comparison of the far-field P-waves from the 2D-1D (solid lines) Shagan River simulations with the tension crack model (dashed lines) at three take off angles for a depth of burial of 200 m.



Comparison of the far-field P-waves from the 2D-1D (solid lines) Shagan River simulations with the tension crack model (dashed lines) at three take off angles for a depth of burial of 300 $\,\mathrm{m}.$ Figure 13.



simulations with the tension crack model (dashed lines) at three take-off angles for a Comparison of the far-field P-waves from the 2D-1D (solid lines) Shagan River depth of burial of 680 $\mathrm{m}.$ Figure 14.

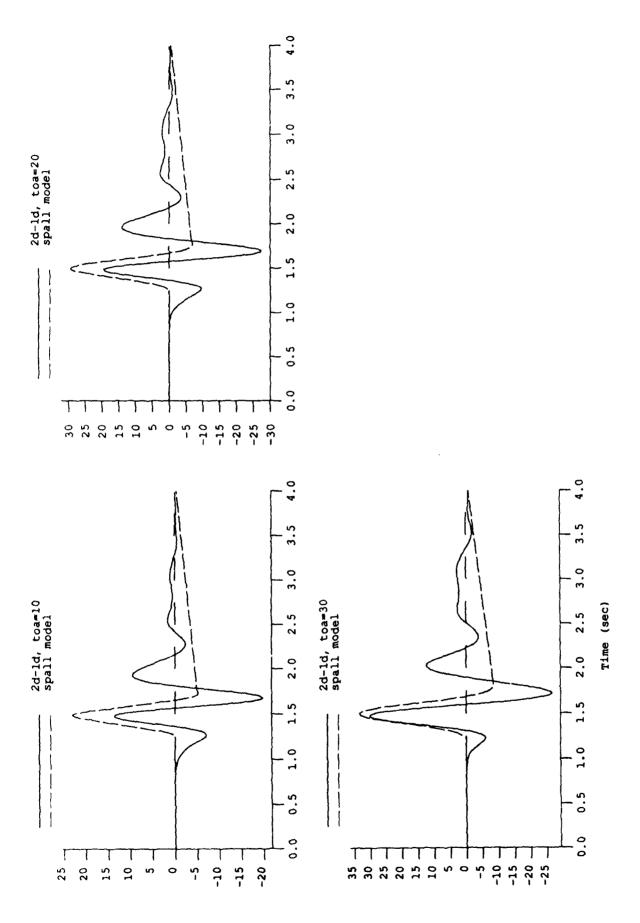


Comparison of the far-field P-waves from the 2D-1D (solid lines) Shagan River simulations with the tension crack model (dashed lines) at three take-off angles for a depth of burial of 980 m. Figure 15.

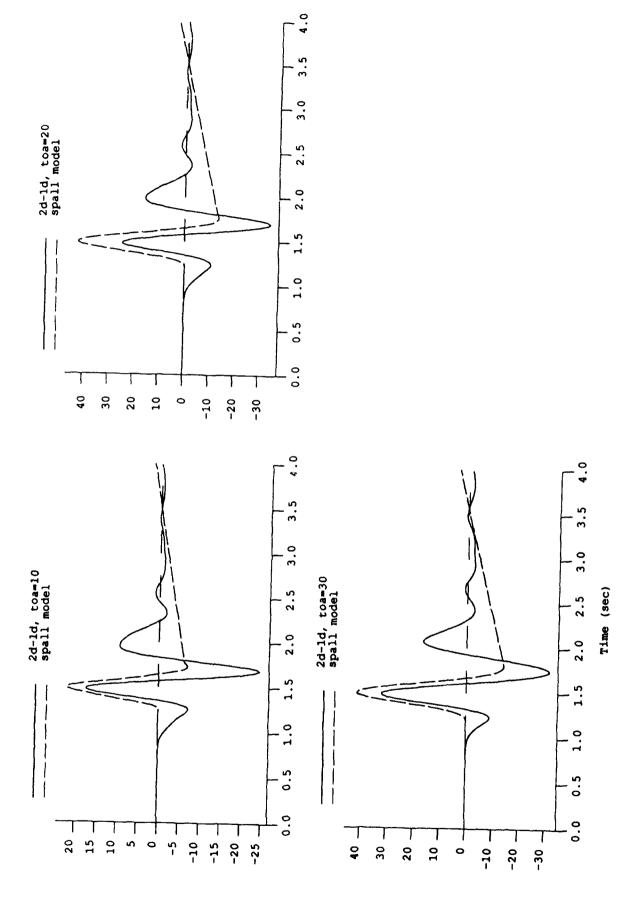
The peak detachment velocity is inferred from field observations from ground motion records at or near ground zero. We can do an analogous measurement by examining the vertical velocity in the finite difference simulation at the free-surface of the grid. We find that the values of v_2 in Table 2.2 agree closely with the ground zero velocities in the simulations.

Using the parameters in Table 3.2, we computed the SV waves from the tension crack model and compared them with the corresponding 2D-1D SV waves. As can be seen in Figures 16 to 19, the comparisons are not as good as the P-waves, especially at the deeper DOB's, where the amplitudes predicted by the model are too small by factors of two to three. Attempts to find a set of parameters which would improve the SV comparisons without degrading the P comparisons were unsuccesful. We note that in all cases, the tension crack models derived from the P-waves underestimate the SV radiation.

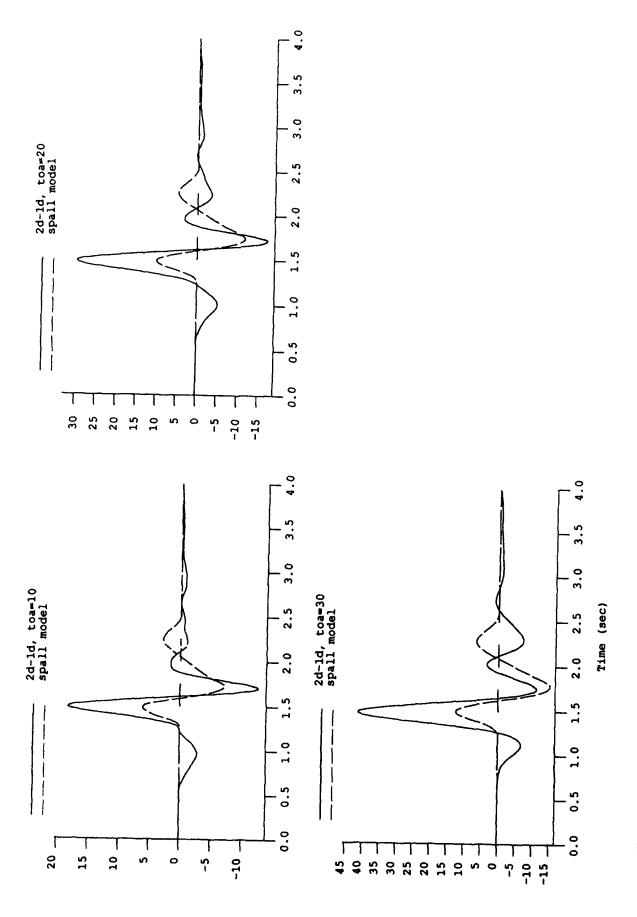
The results of the SV comparisons suggest that the tension crack model is not rich enough in SV radiation. We therefore tried some additions to the model to improve this situation. The additions, a compensated linear vector dipole and a distributed double-couple, are pictured in Figure 20. We hypothesized that processes transpired in the simulations that could be represented as modifications to the isotropic part of the moment tensor. We first chose to represent this as a compensated linear vector dipole or CLVD (e.g., Knopoff and Randall, 1970). The CLVD represents a process akin to squeezing a vertical tube of toothpaste. The moment density for the CLVD is given by



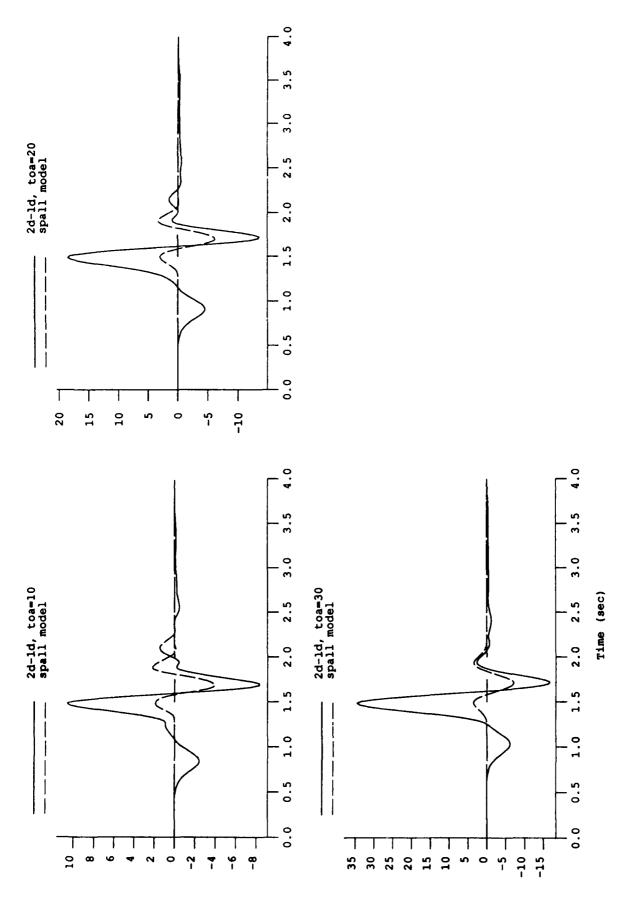
Comparison of the far-field SV-waves from the 2D-1D (solid lines) Shagan River simulations with the tension crack model (dashed lines) at three take-off angles for a depth of burial of 200 m. Figure 16.



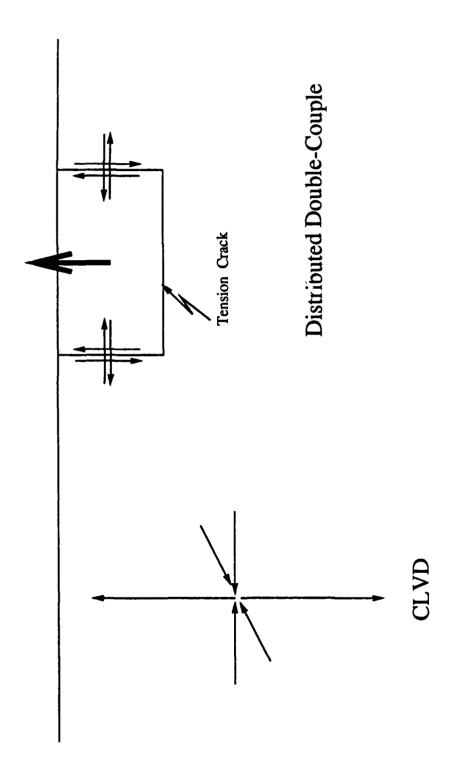
for a Comparison of the far-field SV-waves from the 2D-1D (solid lines) Shagan River simulations with the tension crack model (dashed lines) at three take-off angles depth of burial of 300 $\,\mathrm{m}.$ Figure 17.



simulations with the tension crack model (dashed lines) at three take-off angles for a Comparison of the far-field SV-waves from the 2D-1D (solid lines) Shagan River depth of burial of 680 m. Figure 18.



Comparison of the far-field SV-waves from the 2D-1D (solid lines) Shagan River simulations with the tension crack model (dashed lines) at three take-off angles depth of burial of 980 m. Figure 19.



Alternative SV Sources

Sketch of alternative sources of SV: the compensated linear vector dipole (left) and a distributed double-couple (right). Figure 20.

$$m = s(\xi_1, \xi_2, t) (\lambda + 2\mu) \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

This moment tensor has zero trace. Following the analysis in Section 2, the formulas for the displacements (P along the ray, SV normal to the ray) are similar to Equations (14) and (15),

$$u_{CLVD}^P = \frac{C^P}{R} F_{CLVD}^P(\omega,k) e^{-ik_{\alpha\alpha}\hat{r}} \int_0^a S(\omega,r_0) r_0 dr_0.$$

and

$$u_{CLVD}^{SV} = \frac{C^{SV}}{R} F_{CLVD}^{SV}(\omega,k) e^{-ik_{\beta\alpha}\hat{r}} \int_{0}^{a} S(\omega,r_0) r_0 dr_0 ,$$

where

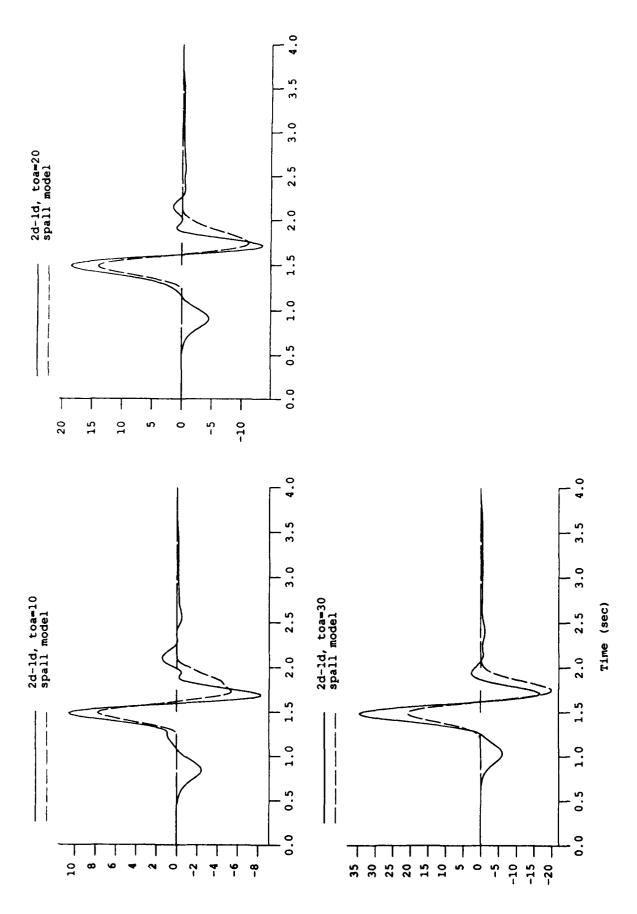
$$F_{CLVD}^{P}(\omega,k) = (\lambda+2\mu) \left(\frac{1}{2}\Delta^{r_0}k - \partial_{z_0}\Delta^{z_0}\right)$$
,

$$F_{CLVD}^{SV}(\omega,k) = (\lambda + 2\mu) \left(\frac{1}{2}\omega^{r_0}k - \partial_{z_0}\omega^{z_0}\right)$$
.

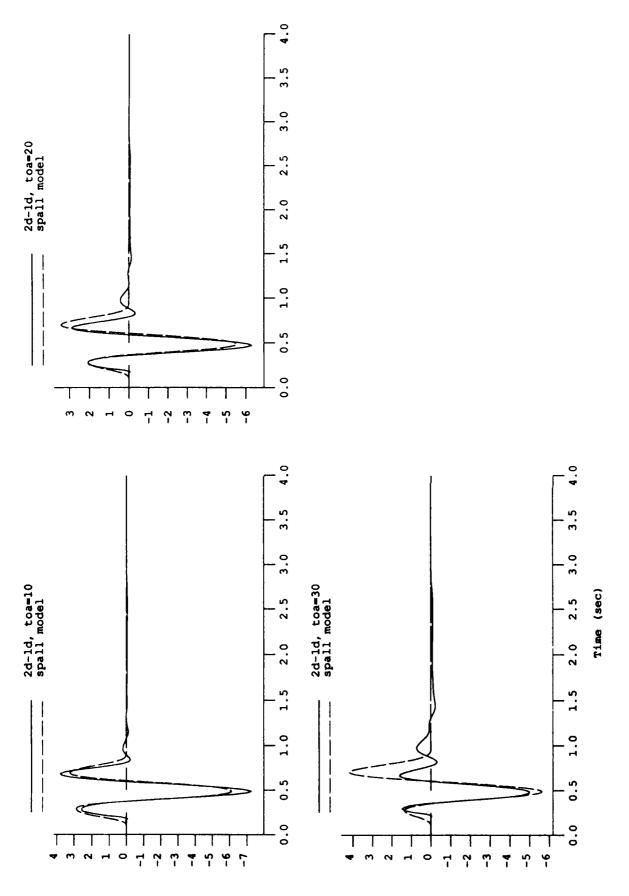
We then formed the sum

$$u = v u_{crack} + (1-v) u_{CLVD}$$

where u_{crack} is the tension crack solution, and $0 \le v \le 1$. We assumed the time and spatial dependence of $S(\omega, r_0)$ was the same for both the tension crack and CLVD. Figures 21 and 22 show the comparisons for the P and SV waves for the DOB=980 case with v = 0 (all CLVD, no tension crack), which we found works best for this DOB. We see that the P wave solutions are changed little except at the shallowest take-off angle (30°), where the second peak in the CLVD solutions is now too large. On the other hand, the comparisons for the SV waves are greatly improved. The shape and



Comparison of the far-field SV-waves from the 2D-1D (solid lines) Shagan River simulations with the CLVD model (dashed lines) (with no tension crack contribution) at three take-off angles for a depth of burial of 980 m Figure 21.

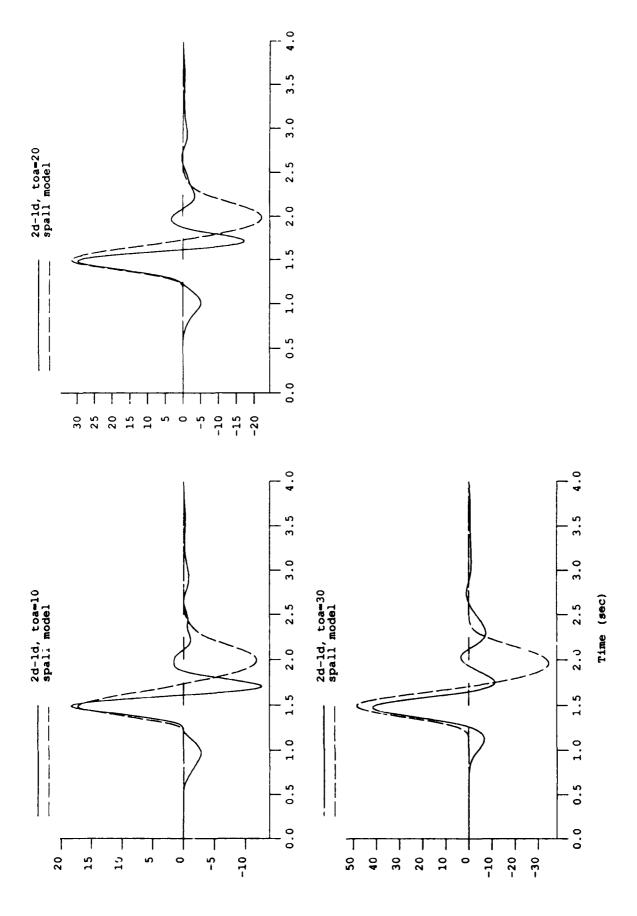


Comparison of the far-field P-waves from the 2D-1D (solid lines) Shagan River simulations with the CLVD model (dashed lines) (with no tension crack contribution) at three take-off angles for a depth of burial of 980 m Figure 22.

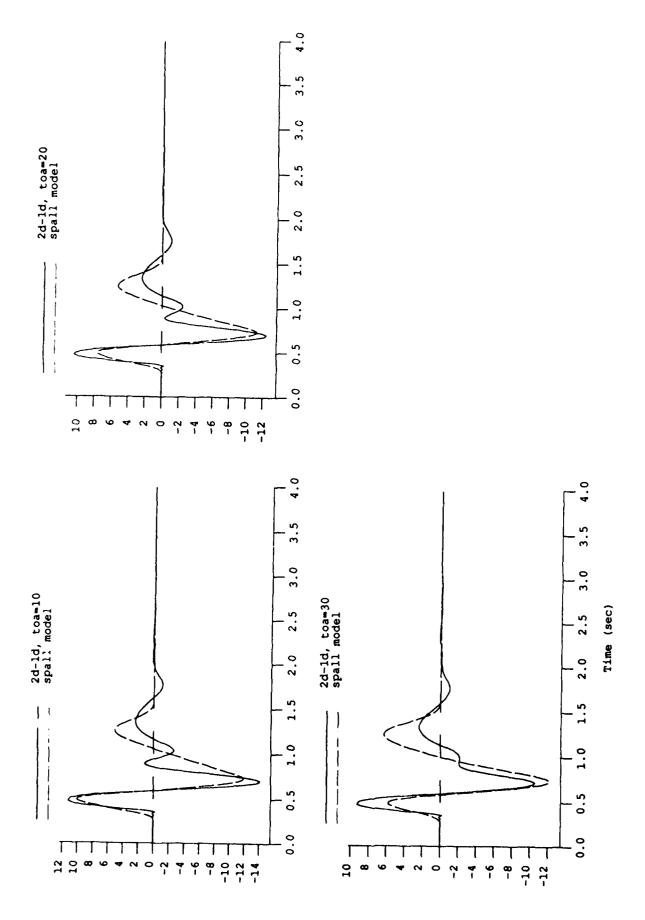
amplitudes agree fairly well. The initial negative part of the 2D-1D signals is a direct S wave from the explosive source. It is not part of the free surface interaction which we are modeling here. For the DOB=680 case, we found that a value of v = 0.5 (equal parts tension crack and CLVD) works better than other choices, but the results are not as good as for DOB=980, as can be seen in Figures 23 and 24. Although the amplitudes of the main peak are matched well, the apparent period and change with take-off angle of the following trough are matched poorly. We find that adding the CLVD source to the tension crack for the shallow DOB's (200 and 300) worsens the comparisons.

Since this approach showed some promise, we also hypothesized that additional sources of shear waves may be emanating from vertical cracks which are the boundaries of a cylinder which moves above the horizontal tension crack. That is, we imagine that the material above the tension crack moves up and down as a unit, shaped as a cylinder whose base is the tension crack. The relative motion along the vertical sides would act as a distributed shear dislocation. Without showing the details, we summarize by saying that after including this source in the computer code, its contribution to the DOB=680 and 980 SV solutions was too small to match the 2D-1D differences.

The tension crack model presented here matches the P waves due to free surface interactions in these simulations very well, but the model includes only part of the SV wave generation mechanisms.



1/2 tension crack contributions (dashed lines) at three take-off angles for a depth of Comparison of 2D-1D far-field SV-waves (solid lines) and results using 1/2 CLVD and burial of 680 m from the Shagan River simulations. Figure 73.



Comparison of 2D-1D far-field P-waves (solid lines) and results using 1/2 CLVD and 1/2 tension crack contributions (dashed lines) at three take-off angles for a depth of burial of 680 m from the Shagan River simulations. Figure 24.

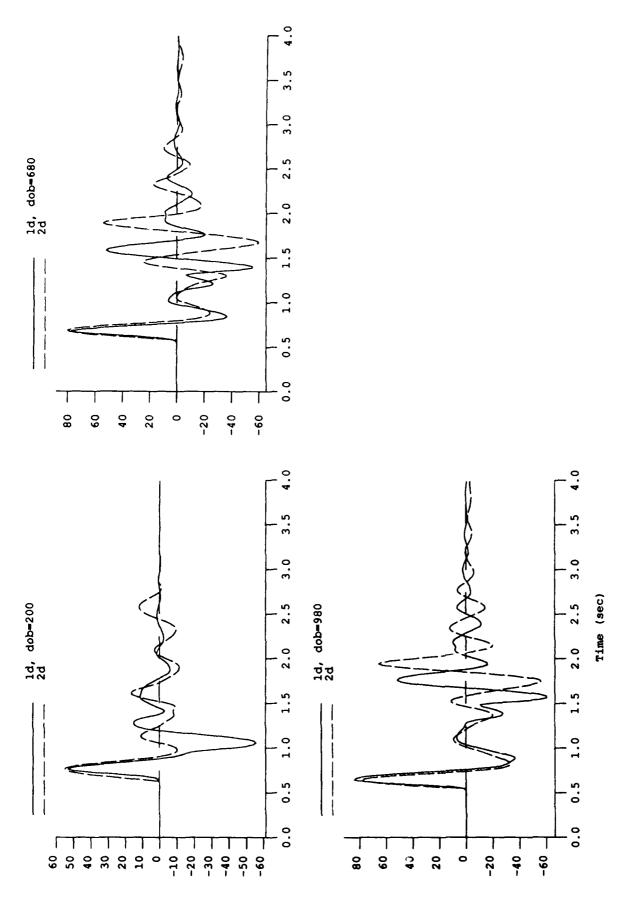
3.2. Pahute Mesa Simulations

The 2D and 1D P-wave signals are overlain in Figures 25 through 27. The calculations were done at DOB's of 200, 680 and 980 m for the Pahute Mesa model, but not at 300 m. The take-off angles $(3.3^{\circ},11.4^{\circ},16.7^{\circ})$ were chosen so that the phase velocities are the same as in the Shagan River simulations above. The first peaks of the 1D and 2D signals align closely. For DOB's 680 and 980, the apparent pP from the 2D waveforms is lagged about 0.2 seconds relative to the elastic pP in the 1D waveforms. The 2D pP amplitudes are attenuated relative to 1D amplitudes for the shallower take-off angles (11.4°) and (16.7°) .

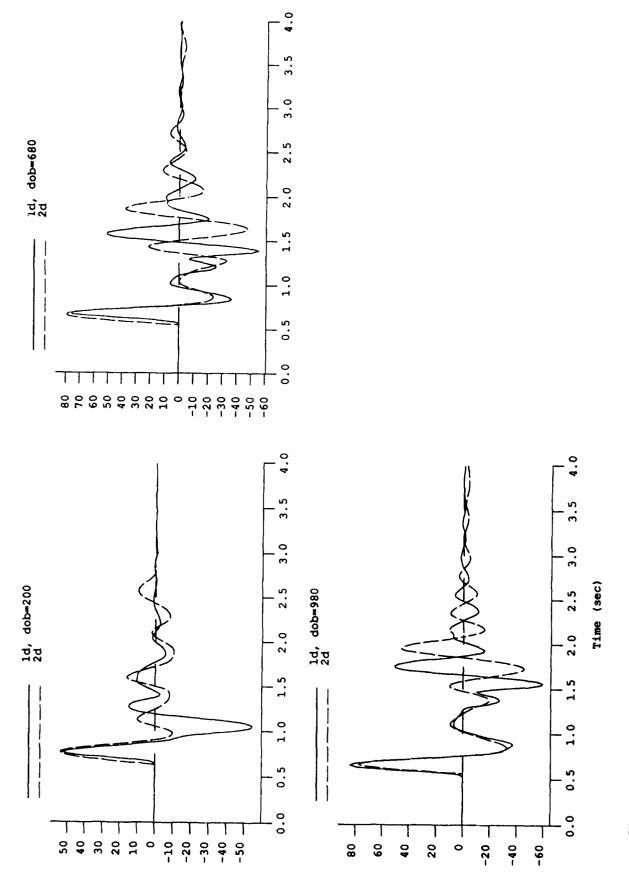
As with the Shagan River simulations, we fit the tension crack model to the 2D-1D difference time series. The results are shown in the comparison plots in Figures 28 through 30. The fits of the model to the 2D-1D signals are generally good for the three DOB's and take-off angles. The parameters of the model are

Table 3.3								
Spall Model Parameters for the Pahute Mesa Simulations								
Depth	Crack	Crack	Minimum	Maximum				
of Burial	Depth	Radius	Detachment	Detachment				
	•		Velocity	Velocity				
z _{exp}	z _s	а	v ₁	ν ₂				
(m)	(m)	(m)	(m/sec)	(m/sec)				
200	150	400	1.1	22				
680	200	2200	1.1	2				
980	150	2200	1.1	2				

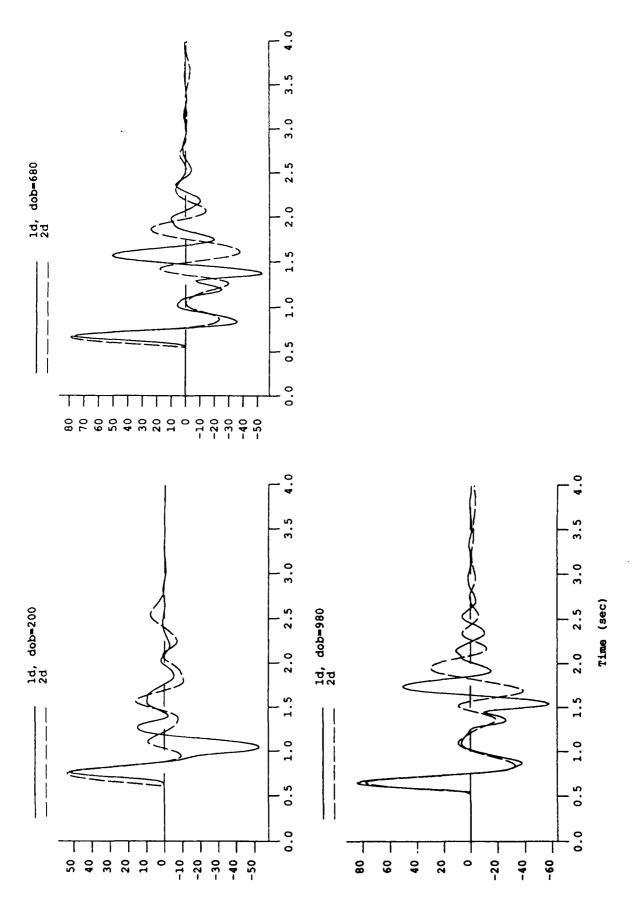
There are several differences between the model parameters derived here and those for the Shagan River simulations. First, in the Shagan case, we found that the solutions were insensitive to the choice of the form of the source function $S(\omega, r_0)$. This is not



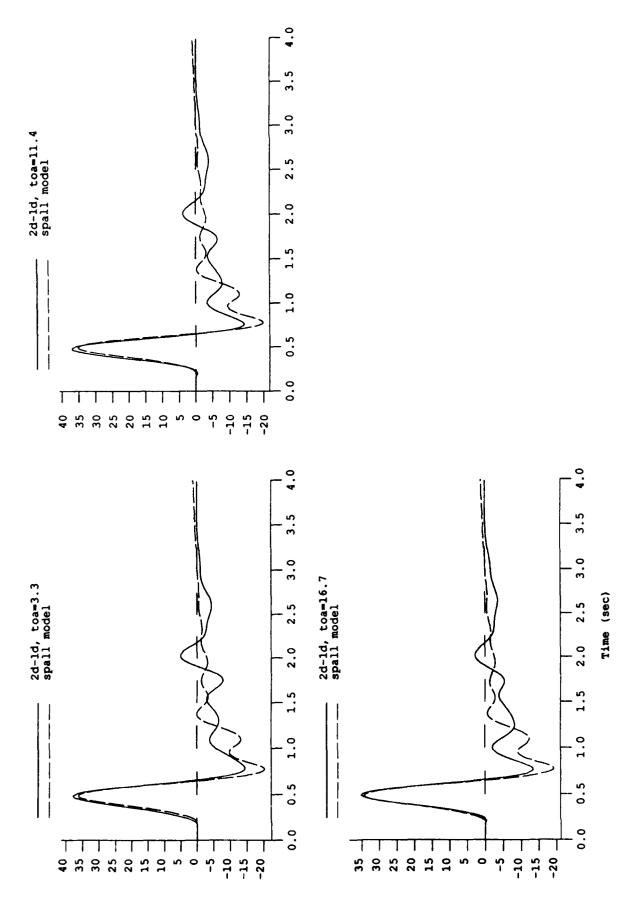
Comparison of the far-field P-waves from the 1D (solid lines) and 2D (dashed lines) Pahute Mesa simulations for three depths of burial at a take-off angle of 3.3°. Figure 25.



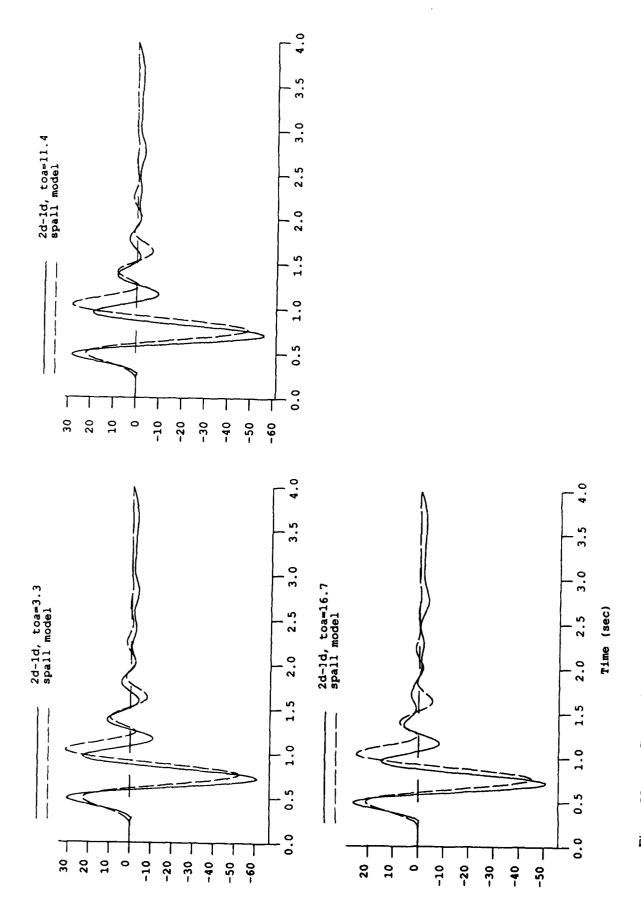
Comparison of the far-field P-waves from the 1D (solid lines) and 2D (dashed lines) Pahute Mesa simulations for three depths of burial at a take-off angle of 11.4°. Figure 26.



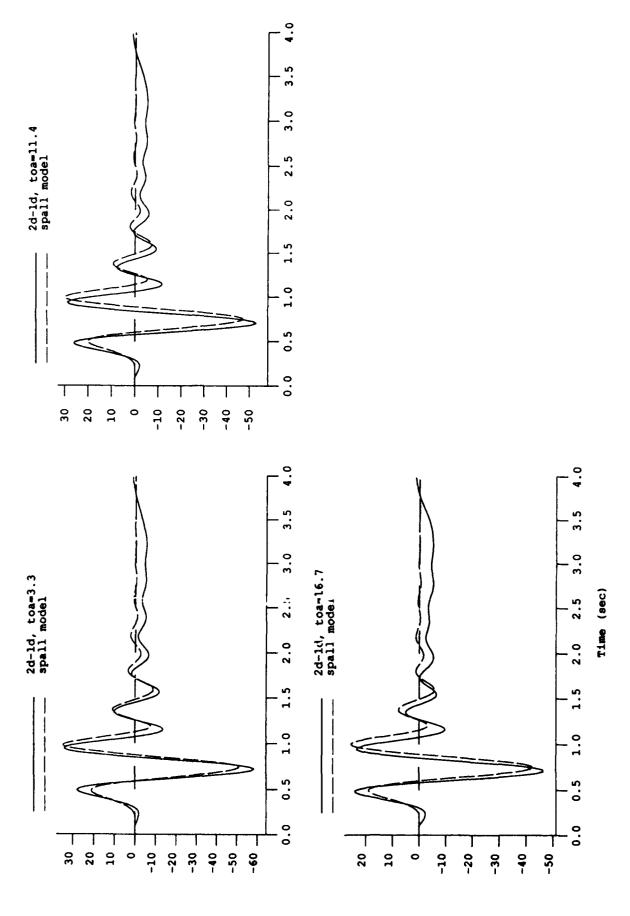
Comparison of the far-field P-waves from the 1D (solid lines) and 2D (dashed lines) Pahute Mesa simulations for three depths of burial at a take-off angle of 16.7°. Figure 27.



Comparison of the far-field P-waves from the 2D-1D (solid lines) Pahute Mesa simulations with the tension crack model (dashed lines) at three take-off angles for a depth of burial of 200 m. Figure 28.



Comparison of the far-field P-waves from the 2D-1D (solid lines) Pahute Mesa simulations with the tension crack model (dashed lines) at three take-off angles for a depth of burial Figure 29.

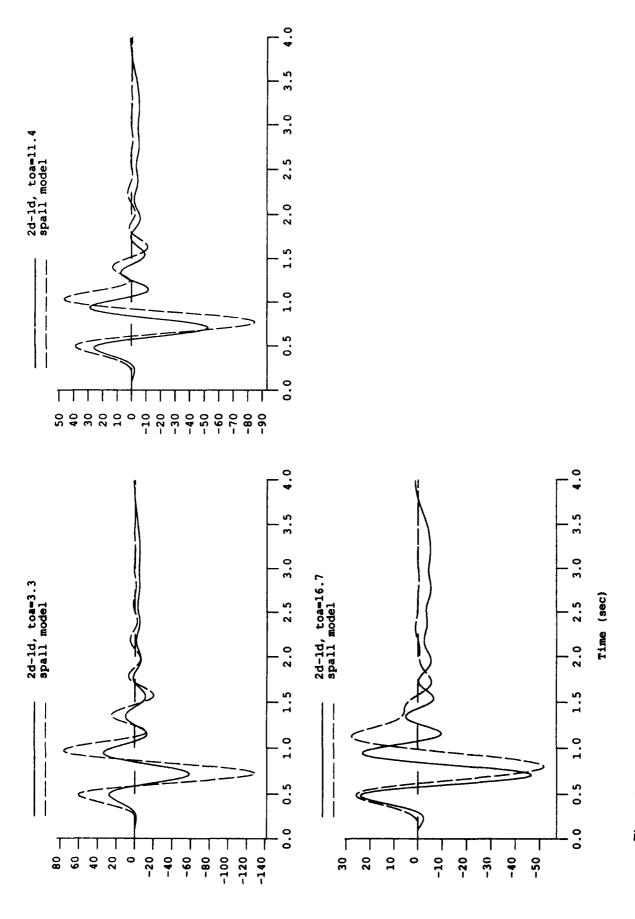


Comparison of the far-field P-waves from the 2D-1D (solid lines) Pahute Mesa sinulations with the tension crack model (dashed lines) at three take-off angles for a depth of burial of 980 m. Figure 30.

the case for the Pahute Mesa runs, where we found that $S(\omega,r_0)$ must be distributed over the crack with the largest values near the center. This is due to the lower wave speeds, and hence phase velocities, in the Pahute Mesa model (Table 3.1). In Figures 28 through 30, a Gaussian spatial dependance with onset lagged by the pP time from the explosion (see Section 2.1 and 2.2) was used. The solutions were not sensitive to the details of the spatial dependance, as long as the maximum was at the center and went to zero at the edge. This spatial dependance was required to match the change in 2D-1D signals with take-off angle. It was not needed for the Shagan River runs because the wave speeds were about twice those for Pahute Mesa. For example, we show the tension crack signals for a constant $S(\omega,r_0)$ for DOB=980 with the 2D-1D signals in Figure 31. It can be seen that the results are not as good as in Figure 29 where the Gaussian spatial dependance was used.

Another feature of the Pahute Mesa simulations that differs from the Shagan River runs is the large change in crack radius between the case for DOB=200 and the other two DOB's. This is presumably due to the shallow layering in the Pahute Mesa earth model. Although the tension crack had a maximum detachment velocity (22 m/sec) similar to Shagan, it occured over a much smaller radius (400 m).

A further difference between the models for the two sites is that the maximum detachment velocities for Pahute Mesa were the same for DOB's 680 and 980, whereas the velocity decreased from DOB=680 to 980 in the Shagan model. This is again attributed to differences in the shallow nonlinear properties.



Comparison of the far-field P-waves from the 2D-1D (solid lines) Pahute Mesa simulations with the tension crack model with constant slip (dashed lines) at three take-off angles for a depth of burial of 980 m. Figure 31.

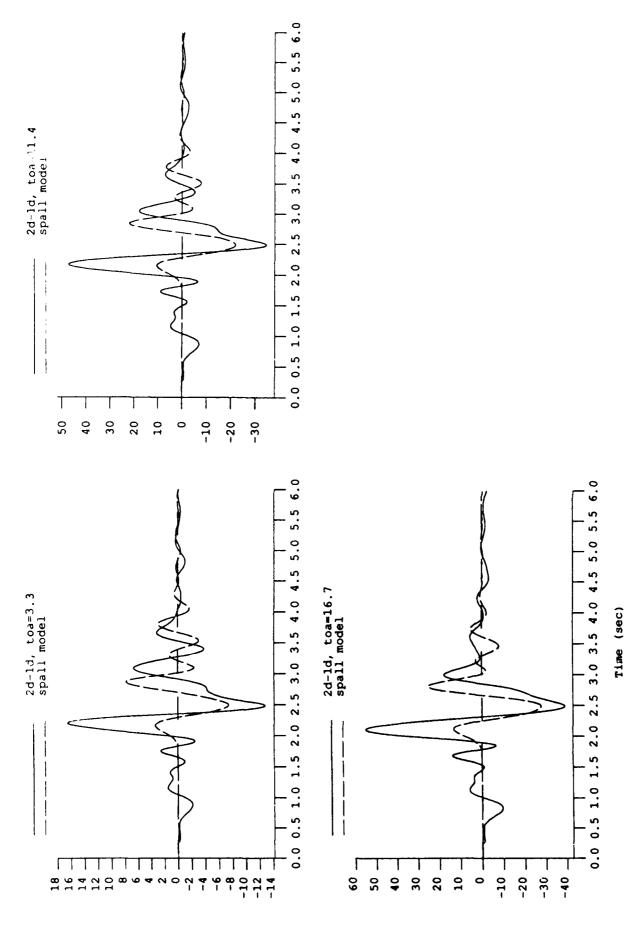
We computed the SV waves for the tension crack using the parameters in Table 3.3, and compared them to the 2D-1D difference waveforms. They are shown in Figure 32, for DOB=680 m. As with the Shagan River simulations, the 2D-1D signals are larger than those from the tension crack. Again this indicates that processes are generating SV waves in the simulations that are not included in the tension crack model.

3.3. Comparisons with Observations

From observations of surface ground motions and of physical manifestations of Pahute Mesa tests, several authors have estimated the parameters of the spall process. In Table 3.4, we compare their results with those for the tension crack model at the optimal DOB (680).

Table 3.4. Spall parameters from field observations and from the tension crack model for Pahute Mesa								
Parameter	Tension Crack	Patton (1990)	Sobel (1978)	Viecelli (1973)	Stump (1985)	Rawson (1988)		
Maximum Velocity (m/sec)	2	6.4		8				
Radius (m)	2200	1750		500		500- 2665		
Momentum (×10 ¹² Nt-s)	7.5	9.2	3.5	0.58				
Mass (×10 ¹² Kg)	5.3	3.5	1.2	0.2	3.0			
Depth (m)	200			110		100- 400		

The authors cited in the table typically expressed their results as scaled values, in which case we used 125 KT, the yield in the simulations. In addition, the values in



Comparison of the far-field SV-waves from the 2D-1D (solid lines) Pahute Mesa simulations with the tension crack model with Gaussian slip distribution (dashed lines) at three take-off angles for a depth of burial of 680 ш. Figure 32.

Table 3.4 are the average values given by the authors. The mean detachment velocity (1.55 m/sec) was used to compute the tension crack momentum, rather than the maximum velocity. The momentum, spall radius and depth from the tension crack model lie within the spread of those inferred from observations. The mass is at the high end while the maximum velocity is at the low end.

It is very difficult to estimate the parameters in Table 3.4 because of a paucity of direct observations. There are typically few surface ground motion sensors, and no sub-surface observations of ground motion or other phenomena such as cracking. Inference of the spall process beyond estimating apparent pP amplitude and travel time from far-field recordings has not been successful. With these limitations in mind, it can be said that the parameters of this study are consistent with published field observations.

4. SUMMARY AND CONCLUSIONS

We show that a simple model can be constructed which generates the far-field P waves of a two-dimensional nonlinear calculation which includes the effects of the free-surface for a range of depths-of-burial. The model which fits the P-waves from the Shagan River simulations underestimates the SV-waves. The model, proposed in its original form by Day, et al. (1983), is based on using a tension crack which opens due to the tension wave from the free surface. The material over the crack travels up with the impulse of the tension wave and returns under the influence of gravity. Stump (1985) modified the original model to include the effects of source by adding an empirical time function based on chemical explosions. The modified model was used by Taylor and Randall (1989) to model regional seismograms. In our formalism presented in this report, we include the effects of source finiteness and those of crustal reverberations. A time dependence is a natural consequence.

The parameters of the model compare favorably with observations based on field data. In addition, McLaughlin, et al. (1990), use the model to compute regional seismograms and find that in the Lg bandwidth, the spall contribution should be comparable to or greater than that of the explosion signal alone. Since the spall model which this the P-waves in our study generates SV-waves that are too small, the spall model may lead to an underestimate of the Lg from spall. Spall, therefore, appears to be a very significant source of Lg.

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CONTRACTORS (UNITED STATES)

Prof. Thomas Ahrens Seismological Lab, 252-21 Division of Geological & Planetary Sciences California Institute of Technology Pasadena, CA 91125

Prof. Charles B. Archambeau CIRES University of Colorado Boulder, CO 80309

Dr. Thomas C. Bache, Jr. Science Applications Int'l Corp. 10260 Campus Point Drive San Diego, CA 92121 (2 copies)

Prof. Muawia Barazangi Institute for the Study of the Continent Cornell University Ithaca, NY 14853

Dr. Douglas R. Baumgardt ENSCO, Inc 5400 Port Royal Road Springfield, VA 22151-2388

Prof. Jonathan Berger IGPP, A-025 Scripps Institution of Oceanography University of California, San Diego La Jolla, CA 92093

Dr. Lawrence J. Burdick Woodward-Clyde Consultants 566 El Dorado Street Pasadena, CA 91109-3245

Dr. Jerry Carter Center for Seismic Studies 1300 North 17th St., Suite 1450 Arlington, VA 22209-2308

Dr. Karl Coyner New England Research, Inc. 76 Olcott Drive White River Junction, VT 05001

Prof. Vernon F. Cormier
Department of Geology & Geophysics
U-45, Room 20/
The University of Connecticut
Storrs, CT 06268

Professor Anton W. Dainty
Earth Resources Laboratory
Massachusetts Institute of Technology
42 Carleton Street
Cambridge, MA 02142

Prof. Steven Day
Department of Geological Sciences
San Diego State University
San Diego, CA 92182

Dr. Zoltan A. Der ENSCO, Inc. 5400 Port Royal Road Springfield, VA 22151-2388

Prof. John Ferguson Center for Lithospheric Studies The University of Texas at Dallas P.O. Box 830688 Richardson, TX 75083-0688

Prof. Stanley Flatte Applied Sciences Building University of California Santa Cruz, CA 95064

Dr. Alexander Florence SRI International 333 Ravenswood Avenue Menlo Park, CA 94025-3493

Prof. Stephen Grand University of Texas at Austin Department of Geological Sciences Austin, TX 78713-7909

Prof. Henry L. Gray Vice Provost and Dean Department of Statistical Sciences Southern Methodist University Dallas, TX 75275

Dr. Indra Gupta Teledyne Geotech 314 Montgomery Street Alexandria, VA 22314

Prof. David G. Harkrider
Seismological Laboratory
Division of Geological & Planetary Sciences
California Institute of Technology
Pasadena, CA 91125

Prof. Donald V. Helmberger Seismological Laboratory Division of Geological & Planetary Sciences California Institute of Technology Pasadena, CA 91125

Prof. Eugene Herrin
Institute for the Study of Earth and Man
GeophysicalLaboratory
Southern Methodist University
Dallas, TX 75275

Prof. Robert B. Herrmann
Department of Earth & Atmospheric Sciences
St. Louis University
St. Louis, MO 63156

Prof. Bryan Isacks Cornell University Department of Geological Sciences SNEE Hall Ithaca, NY 14850

Dr. Rong-Song Jih Teledyne Geotech 314 Montgomery Street Alexandria, VA 22314

Prof. Lane R. Johnson Seismographic Station University of California Berkeley, CA 94720

Prof. Alan Kafka
Department of Geology & Geophysics
Boston College
Chestnut Hill, MA 02167

Dr. Richard LaCoss MIT-Lincoln Laboratory M-200B P. O. Box 73 Lexington, MA 02173-0073 (3 copies)

Prof Fred K. Lamb
University of Illinois at Urbana-Champaign
Department of Physics
1110 West Green Street
Urbana, IL 61801

Prof. Charles A. Langston Geosciences Department 403 Deike Building The Pennsylvania State University University Park, PA 16802 Prof. Thorne Lay Institute of Tectonics Earth Science Board University of California, Santa Cruz Santa Cruz, CA 95064

Prof. Arthur Lerner-Lam Lamont-Doherty Geological Observatory of Columbia University Palisades, NY 10964

Dr. Christopher Lynnes Teledyne Geotech 314 Montgomery Street Alexandria, VA 22314

Prof. Peter Malin University of California at Santa Barbara Institute for Crustal Studies Santa Barbara, CA 93106

Dr. Randolph Martin, III New England Research, Inc. 76 Olcott Drive White River Junction, VT 05001

Dr. G. McCartor Southern Methodist University Dept of Physics Dallas, TX 75275

Prof. Thomas V. McEvilly Seismographic Station University of California Berkeley, CA 94720

Dr. Keith L. McLaughlin S-CUBED A Division of Maxwell Laboratory P.O. Box 1620 La Jolla, CA 92038-1620

Prof. William Menke Lamont-Doherty Geological Observatory of Columbia University Palisades, NY 10964

Stephen Miller SRI International 333 Ravenswood Avenue Box AF 116 Menlo Park, CA 94025-3493 Prof. Bernard Minster IGPP, A-025 Scripps Institute of Oceanography University of California, San Diego La Jolla, CA 92093

Prof. Brian J. Mitchell Department of Earth & Atmospheric Sciences St. Louis University St. Louis, MO 63156

Mr. Jack Murphy S-CUBED, A Division of Maxwell Laboratory 11800 Sunrise Valley Drive Suite 1212 Reston, VA 22091 (2 copies)

Dr. Bao Nguyen GL/LWH Hanscom AFB, MA 01731-5000

Prof. John A. Orcutt IGPP, A-025 Scripps Institute of Oceanography University of California, San Diego La Jolla, CA 92093

Prof. Keith Priestley University of Cambridge Bullard Labs, Dept. of Earth Sciences Madingley Rise, Madingley Rd. Cambridge CB3 OEZ, ENGLAND

Prof. Paul G. Richards Lamont Doherty Geological Observatory of Columbia University Palisades, NY 10964

Dr. Wilmer Rivers Teledyne Geotech 314 Montgomery Street Alexandria, VA 22314

Prof. Charles G. Sammis Center for Earth Sciences University of Southern California University Park Los Angeles, CA 90089-0741

Prof. Christopher H. Scholz Lamont-Doherty Geological Observatory of Columbia University Palisades, NY 10964 Thomas J. Sereno, Jr. Science Application Int'l Corp. 10260 Campus Point Drive San Diego, CA 92121

Prof. David G. Simpson Lamont-Doherty Geological Observatory of Columbia University Palisades, NY 10964

Dr. Jeffrey Stevens S-CUBED A Division of Maxwell Laboratory P.O. Box 1620 La Jolla, CA 92038-1620

Prof. Brian Stump Institute for the Study of Earth & Man Geophysical Laboratory Southern Methodist University Dallas, TX 75275

Prof. Jeremiah Sullivan University of Illinois at Urbana-Champaign Department of Physics 1110 West Green Street Urbana, IL 61801

Prof. Clifford Thurber University of Wisconsin-Madison Department of Geology & Geophysics 1215 West Dayton Street Madison, WS 53706

Prof. M. Nafi Toksoz
Earth Resources Lab
Massachusetts Institute of Technology
42 Carleton Street
Cambridge, MA 02142

Prof. John E. Vidale University of California at Santa Cruz Seismological Laboratory Santa Cruz, CA 95064

Prof. Terry C. Wallace Department of Geosciences Building #77 University of Arizona Tucson, AZ 85721

Dr. Raymond Willeman GL/LWH Hanscom AFB, MA 01731-5000

Dr. Lorraine Wolf GL/LWH Hanscom AFB, MA 01731-5000 Dr. Monem Abdel-Gawad Rockwell International Science Center 1049 Camino Dos Rios Thousand Oaks, CA 91360

Prof. Keiiti Aki Center for Earth Sciences University of Southern California University Park Los Angeles, CA 90089-0741

Prof. Shelton S. Alexander Geosciences Department 403 Deike Building The Pennsylvania State University University Park, PA 16802

Dr. Kenneth Anderson BBNSTC Mail Stop 14/1B Cambridge, MA 02238

Dr. Ralph Archuleta
Department of Geological Sciences
University of California at Santa Barbara
Santa Barbara, CA 93102

Dr. Jeff Barker Department of Geological Sciences State University of New York at Binghamton Vestal, NY 13901

Dr. Susan Beck Department of Geosciences, Bldg # 77 University of Arizona Tucson, AZ 85721

Dr. T.J. Bennett S-CUBED A Division of Maxwell Laboratory 11800 Sunrise Valley Drive, Suite 1212 Reston, VA 22091

Mr. William J. Best 907 Westwood Drive Vienna, VA 22180

Dr. N. Biswas Geophysical Institute University of Alaska Fairbanks, AK 99701 Dr. G.A. Bollinger
Department of Geological Sciences
Virginia Polytechnical Institute
21044 Derring Hall
Blacksburg, VA 24061

Dr. Stephen Bratt Center for Seismic Studies 1300 North 17th Street Suite 1450 Arlington, VA 22209

Michael Browne Teledyne Geotech 3401 Shiloh Road Garland, TX 75041

Mr. Roy Burger 1221 Serry Road Schenectady, NY 12309

Dr. Robert Burridge Schlumberger-Doll Research Center Old Quarry Road Ridgefield, CT 06877

Dr. W. Winston Chan Teledyne Geotech 314 Montgomery Street Alexandria, VA 22314-1581

Dr. Theodore Cherry Science Horizons, Inc. 710 Encinitas Blvd., Suite 200 Encinitas, CA 92024 (2 copies)

Prof. Jon F. Claerbout Department of Geophysics Stanford University Stanford, CA 94305

Prof. Robert W. Clayton Seismological Laboratory Division of Geological & Planetary Sciences California Institute of Technology Pasadena, CA 91125

Prof. F. A Dahlen Geological and Geophysical Sciences Princeton University Princeton, NJ 08544-0636 Prof. Adam Dziewonski Hoffman Laboratory Harvard University 20 Oxford St Cambridge, MA 02138

Prof. John Ebel
Department of Geology & Geophysics
Boston College
Chestnut Hill, MA 02167

Eric Fielding SNEE Hall INSTOC Cornell University Ithaca, NY 14853

Prof. Donald Forsyth Department of Geological Sciences Brown University Providence, RI 02912

Dr. Cliff Frolich Institute of Geophysics 8701 North Mopac Austin, TX 78759

Dr. Anthony Gangi Texas A&M University Department of Geophysics College Station, TX 77843

Dr. Freeman Gilbert IGPP, A-025 Scripps Institute of Oceanography University of California La Jolla, CA 92093

Mr. Edward Giller Pacific Sierra Research Corp. 1401 Wilson Boulevard Arlington, VA 22209

Dr. Jeffrey W. Given SAIC 10260 Campus Point Drive San Diego, CA 92121

Prof. Roy Greenfield Geosciences Department 403 Deike Building The Pennsylvania State University University Park, PA 16802 Dan N. Hagedorn
Battelle
Pacific Northwest Laboratories
Battelle Boulevard
Richland, WA 99352

Kevin Hutchenson Department of Earth Sciences St. Louis University 3507 Laclede St. Louis, MO 63103

Dr. Hans Israelsson Center for Seismic Studies 1300 N. 17th Street, Suite 1450 Arlington, VA 22209-2308

Prof. Thomas H. Jordan
Department of Earth, Atmospheric
and Planetary Sciences
Massachusetts Institute of Technology
Cambridge, MA 32139

Robert C. Kemerait ENSCO, Inc. 445 Pineda Court Melbourne, FL 32940

William Kikendall Teledyne Geotech 3401 Shiloh Road Garland, TX 75041

Prof. Leon Knopoff
University of California
Institute of Geophysics & Planetary Physics
Los Angeles, CA 90024

Prof. L. Timothy Long School of Geophysical Sciences Georgia Institute of Technology Atlanta, GA 30332

Prof. Art McGarr Mail Stop 977 Geological Survey 345 Middlefield Rd. Menlo Park, CA 94025

Dr. George Mellman Sierra Geophysics 11255 Kirkland Way Kirkland, WA 98033 Prof. John Nabelek College of Oceanography Oregon State University Corvallis, OR 97331

Prof. Geza Nagy University of California, San Diego Department of Ames, M.S. B-010 La Jolla, CA 92093

Prof. Amos Nur Department of Geophysics Stanford University Stanford, CA 94305

Prof. Jack Oliver Department of Geology Cornell University Ithaca, NY 14850

Prof. Robert Phinney Geological & Geophysical Sciences Princeton University Princeton, NJ 08544-0636

Dr. Paul Pomeroy Rondout Associates P.O. Box 224 Stone Ridge, NY 12484

Dr. Jay Pulli RADIX System, Inc. 2 Taft Court, Suite 203 Rockville, MD 20850

Dr. Norton Rimer S-CUBED A Division of Maxwell Laboratory P.O. Box 1620 La Jolla, CA 92038-1620

Prof. Larry J. Ruff
Department of Geological Sciences
1006 C.C. Little Building
University of Michigan
Ann Arbor, MI 48109-1063

Dr. Richard Sailor TASC Inc. 55 Walkers Brook Drive Reading, MA 01867 Dr. Susan Schwartz Institute of Tectonics 1156 High St. Santa Cruz, CA 95064

John Sherwin Teledyne Geotech 3401 Shiloh Road Garland, TX 75041

Dr. Matthew Sibol Virginia Tech Seismological Observatory 4044 Derring Hall Blacksburg, VA 24061-0420

Prof. Robert Smith Department of Geophysics University of Utah 1400 East 2nd South Salt Lake City, UT 84112

Dr. Stewart W. Smith Geophysics AK-50 University of Washington Seattle, WA 98195

Dr. George Sutton Rondout Associates P.O. Box 224 Stone Ridge, NY 12484

Prof. L. Sykes Lamont-Doherty Geological Observatory of Columbia University Palisades, NY 10964

Prof. Pradeep Talwani Department of Geological Sciences University of South Carolina Columbia, SC 29208

Prof. Ta-liang Teng Center for Earth Sciences University of Southern California University Park Los Angeles, CA 90089-0741

Dr. R.B. Tittmann Rockwell International Science Center 1049 Camino Dos Rios P.O. Box 1085 Thousand Oaks, CA 91360 Dr. Gregory van der Vink IRIS, Inc. 1616 North Fort Myer Drive Suite 1440 Arlington, VA 22209

Professor Daniel Walker University of Hawaii Institute of Geophysics Honolulu, HI 96822

William R. Walter Seismological Laboratory University of Nevada Reno, NV 89557

Dr. Gregory Wojcik Weidlinger Associates 4410 El Camino Real Suite 110 Los Altos, CA 94022

Prof. John H. Woodhouse Hoffman Laboratory Harvard University 20 Oxford St. Cambridge, MA 02138

Prof. Francis T. Wu Department of Geological Sciences State University of New York at Binghamton Vestal, NY 13901

Dr. Gregory B. Young ENSCO, Inc. 54(0) Port Royal Road Springfield, VA 22151-2388

GOVERNMENT

Dr. Ralph Alewine III DARPA/NMRO 1400 Wilson Boulevard Arlington, VA 22209-2308

Mr. James C. Battis GL/LWH Hanscom AFB, MA 01731-5000

Dr Robert Blandford AFTAC/TT Center for Seismic Studies 1300 No. 17th St, Suite 1450 Arlington, VA 22209

Eric Chael Division 9241 Sandia Laboratory Albuquerque, NM 87185

Dr. John J. Cipar GL/LWH Hanscom AFB, MA 01731-5000

Cecil Davis Group P-15, Mail Stop D406 P.O. Box 1663 Los Alamos National Laboratory Los Alamos, NM 87544

Mr. Jeff Duncan Office of Congressman Markey 2133 Rayburn House Bldg. Washington, DC 20515

Dr. Jack Evernden USGS - Earthquake Studies 345 Middlefield Road Menlo Park, CA 94025

Art Frankel USGS 922 National Center Reston, VA 22092

Dr. Dale Glover DIA/DT-1B Washington, DC 20301 Dr. T. Hanks USGS Nat'l Earthquake Research Center 345 Middlefield Road Menlo Park, CA 94025

Dr. James Hannon Lawrence Livermore Nat'l Laboratory P.O. Box 808 Livermore, CA 94550

Paul Johnson ESS-4, Mail Stop J979 Los Alamos National Laboratory Los Alamos, NM 87545

Janet Johnston GL/LWH Hanscom AFB, MA 01731-5000

Dr. Katharine Kadinsky-Cade GL/LWH Hanscom AFB, MA 01731-5000

Ms. Ann Kerr IGPP, A-025 Scripps Institute of Oceanography University of California, San Diego La Jolla, CA 92093

Dr. Max Koontz US Dept of Energy/DP 5 Forrestal Building 1000 Independence Avenue Washington, DC 20585

Dr. W.H.K. Lee Office of Earthquakes, Volcanoes, & Engineering 345 Middlefield Road Menlo Park, CA 94025

Dr. William Leith U.S. Geological Survey Mail Stop 928 Reston, VA 22092

Dr. Richard Lewis Director, Earthquake Engineering & Geophysics U.S. Army Corps of Engineers Box 631 Vicksburg, MS 39180 James F. Lewkowicz GL/LWH Hanscom AFB, MA 01731-5000

Mr. Alfred Lieberman ACDA/VI-OA'State Department Bldg Room 5726 320 - 21st Street, NW Washington, DC 20451

Stephen Mangino GL/LWH Hanscom AFB, MA 01731-5000

Dr. Robert Masse Box 25046, Mail Stop 967 Denver Federal Center Denver, CO 80225

Art McGarr U.S. Geological Survey, MS-977 345 Middlefield Road Menlo Park, CA 94025

Richard Morrow ACDA/VI, Room 5741 320 21st Street N.W Washington, DC 20451

Dr. Keith K. Nakanishi Lawrence Livermore National Laboratory P.O. Box 808, L-205 Livermore, CA 94550

Dr. Carl Newton Los Alamos National Laboratory P.O. Box 1663 Mail Stop C335, Group ESS-3 Los Alamos, NM 87545

 Dr. Kenneth H. Olsen Los Alamos Scientific Laboratory P.O. Box 1663

 Mail Stop D-406 Los Alamos, NM 87545

Howard J. Patton Lawrence Livermore National Laboratory P.O. Box 808, L-205 Livermore, CA 94550 Mr. Chris Paine
Office of Senator Kennedy
SR 315
United States Senate
Washington, DC 20510

Colonel Jerry J. Perrizo AFOSR/NP, Building 410 Bolling AFB Washington, DC 20332-6448

Dr. Frank F. Pilotte HQ AFTAC/TT Patrick AFB, FL 32925-6001

Katie Poley CIA-OSWR/NED Washington, DC 20505

Mr. Jack Rachlin U.S. Geological Survey Geology, Rm 3 C136 Mail Stop 928 National Center Reston, VA 22092

Dr. Robert Reinke WL/NTESG Kirtland AFB, NM 87117-6008

Dr. Byron Ristvet HQ DNA, Nevada Operations Office Attn: NVCG P.O. Box 98539 Las Vegas, NV 89193

Dr. George Rothe HQ AFTAC/TTR Patrick AFB, FL 32925-6001

Dr. Alan S. Ryall, Jr. DARPA/NMRO 1400 Wilson Boulevard Arlington, VA 22209-2308

Dr. Michael Shore Defense Nuclear Agency/SPSS 6801 Telegraph Road Alexandria, VA 22310 Dr. Albert Smith Los Alamos National Laboratory L-205 P. O. Box 808 Livermore, CA 94550

Donald L. Springer Lawrence Livermore National Laboratory L-205 P. O. Box 808 Livermore, CA 94550

Mr. Charles L. Taylor GL/LWG Hanscom AFB, MA 01731-5000

Dr. Steven R. Taylor Lawrence Livermore National Laboratory L-205 P. O. Box 808 Livermore, CA 94550

Dr. Larry Turnbull CIA-OSWR/NED Washington, DC 20505

Dr. Eileen Vergi. o Lawrence Livermore National Laboratory L-205 P. O. Box 808 Livermore, CA 94550

Dr. Thomas Weaver Los Alamos National Laboratory P.O. Box 1663, Mail Stop C335 Los Alamos, NM 87545

J.J. Zucca Lawrence Livermore National Laboratory P. O. Box 808 Livermore, CA 94550

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CONTRACTORS (Foreign)

Dr. Ramon Cabre, S.J. Observatorio San Calixto Casilla 5939 La Paz, Bolivia

- Prof. Hans-Peter Harjes
 Institute for Geophysik
 Ruhr University/Bochum
 P.O. Box 102148
- ~ 4630 Bochum 1, FRG

Prof. Eystein Husebye NTNF/NORSAR P.O. Box 51 N-2007 Kjeller, NORWAY

Prof. Brian L.N. Kennett Research School of Earth Sciences Institute of Advanced Studies G.P.O. Box 4 Canberra 2601, AUSTRALIA

Dr. Bernard Massinon Societe Radiomana 27 rue Claude Bernard 75005 Paris, FRANCE (2 Copies)

Dr. Pierre Mecheler Societe Radiomana 27 rue Claude Bernard 75005 Paris, FRANCE

Dr. Svein Mykkeltveit NTNF/NORSAR P.O. Box 51 N-2007 Kjeller, NORWAY

FOREIGN (Others)

Dr. Peter Basham
Earth Physics Branch
Geological Survey of Canada
1 Observatory Crescent
Ottawa, Ontario, CANADA K1A 0Y3

Dr. Eduard Berg Institute of Geophysics University of Hawaii Honolulu, HI 96822

Dr. Michel Bouchon I.R.I.G.M.-B.P. 68 38402 St. Martin D'Heres Cedex, FRANCE

Dr. Hilmar Bungum NTNF/NÖRSAR P.O. Box 51 N-2007 Kjeller, NORWAY

Dr. Michel Campillo
Observatoire de Grenoble
LR.LG.M.-B.P. 53
38041 Grenoble, FRANCE

Dr. Kin Yip Chun Geophysics Division Physics Department University of Toronto Ontario, CANADA M5S 1A7

Dr. Alan Douglas Ministry of Defense Blacknest, Brimpton Reading RG7-4RS, UNITED KINGDOM

Dr. Roger Hansen NTNF/NORSAR P.O. Box 51 N-2007 Kjeller, NORWAY

Dr. Manfred Henger Federal Institute for Geosciences & Nat'l Res. Postfach 510153 D-3000 Hanover 51, FRG

Ms. Eva Johannisson Senior Research Officer National Defense Research Inst. P.O. Box 27322 S-102 54 Stockholm, SWEDEN Dr. Fekadu Kebede Seismological Section Box 12019 S-750 Uppsala, SWEDEN

Dr. Tormod Kvaerna NTNF/NORSAR P.O. Box 51 N-2007 Kjeller, NORWAY

Dr. Peter Marshal Procurement Executive Ministry of Defense Blacknest, Brimpton Reading FG7-4RS, UNITED KINGDOM

Prof. Ari Ben-Menahem Department of Applied Mathematics Weizman Institute of Science Rehovot, ISRAEL 951729

Dr. Robert North Geophysics Division Geological Survey of Canada 1 Observatory Crescent Ottawa. Ontario, CANADA K1A 0Y3

Dr. Frode Ringdal NTNF/NORSAR P.O. Box 51 N-2007 Kjeller, NORWAY

Dr. Jorg Schlittenhardt Federal Institute for Geosciences & Nat'l Res. Postfach 510153 D-3000 Hannover 51, FEDERAL REPUBLIC OF GERMANY